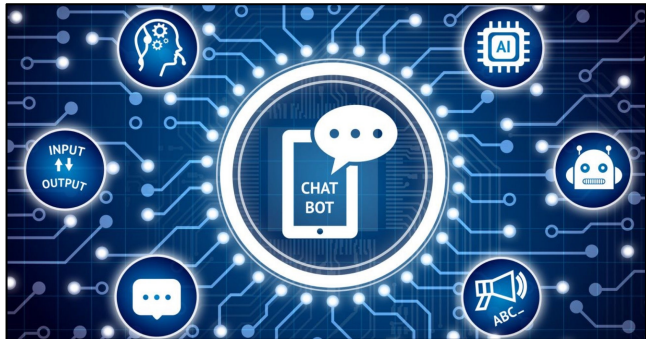


Practical Algorithms from in-depth understanding of LLM behaviors

Yuandong Tian
Research Scientist Director
Meta Superintelligence Lab
(FAIR)



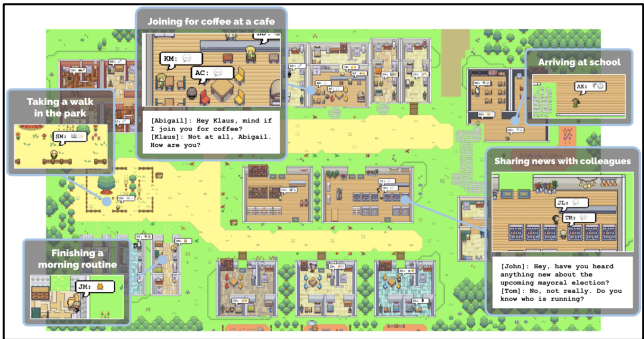
Large Language Models (LLMs)



Conversational AI



Content Generation



AI Agents

Standard Prompting	Chain of Thought Prompting
Input Q: Roger has 5 tennis balls. He buys 2 more cans of tennis balls. Each can has 3 tennis balls. How many tennis balls does he have now? A: The answer is 11. Q: The cafeteria had 23 apples. If they used 20 to make lunch and bought 6 more, how many apples do they have?	Input Q: Roger has 5 tennis balls. He buys 2 more cans of tennis balls. Each can has 3 tennis balls. How many tennis balls does he have now? A: Roger started with 5 balls. 2 cans of 3 tennis balls each is 6 tennis balls. $5 + 6 = 11$. The answer is 11. Q: The cafeteria had 23 apples. If they used 20 to make lunch and bought 6 more, how many apples do they have?
Model Output A: The answer is 27. ❌	Model Output A: The cafeteria had 23 apples originally. They used 20 to make lunch. So they had $23 - 20 = 3$. They bought 6 more apples, so they have $3 + 6 = 9$. The answer is 9. ✅

Reasoning



Planning

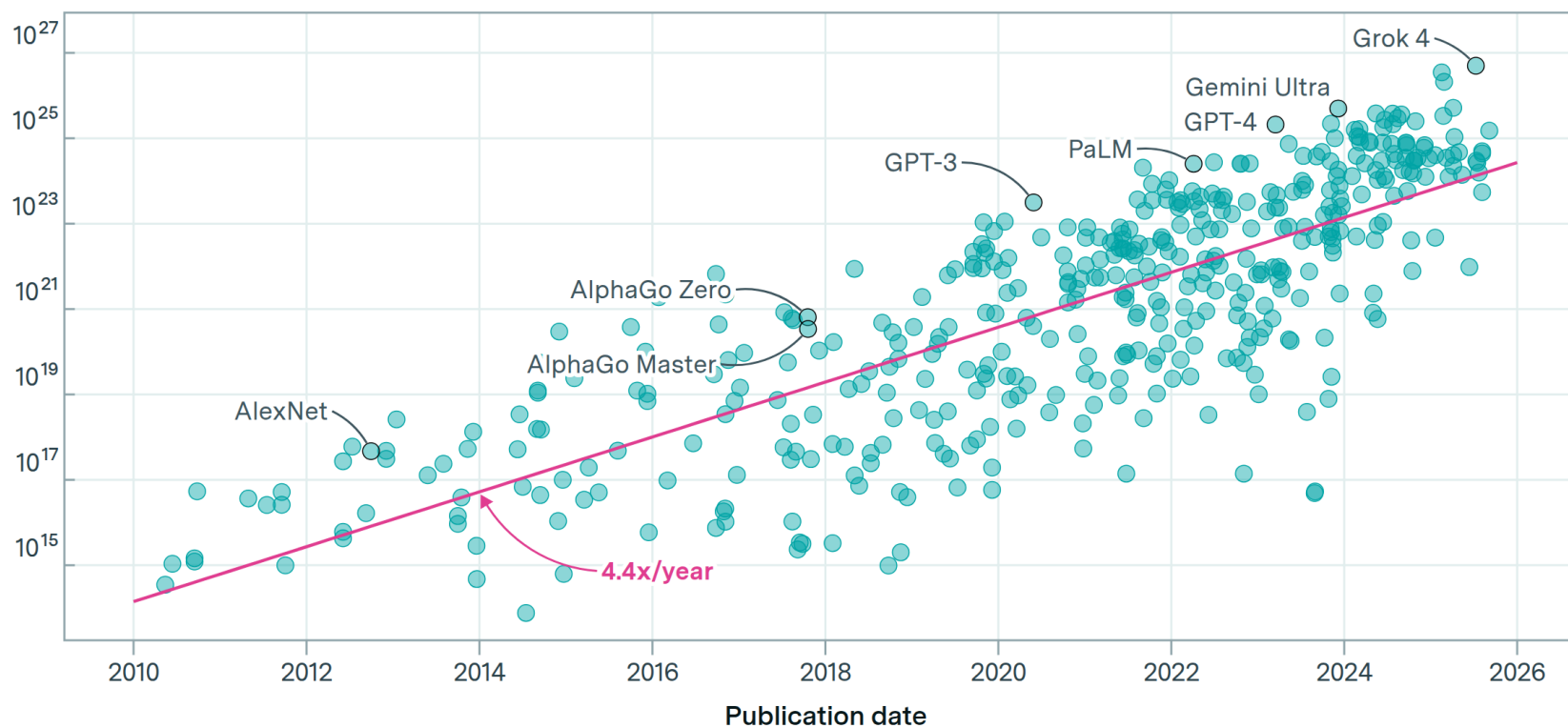
The Progress of Large Models

Training compute of notable models

EPOCH AI

Training compute (FLOP)

443 models



CC-BY

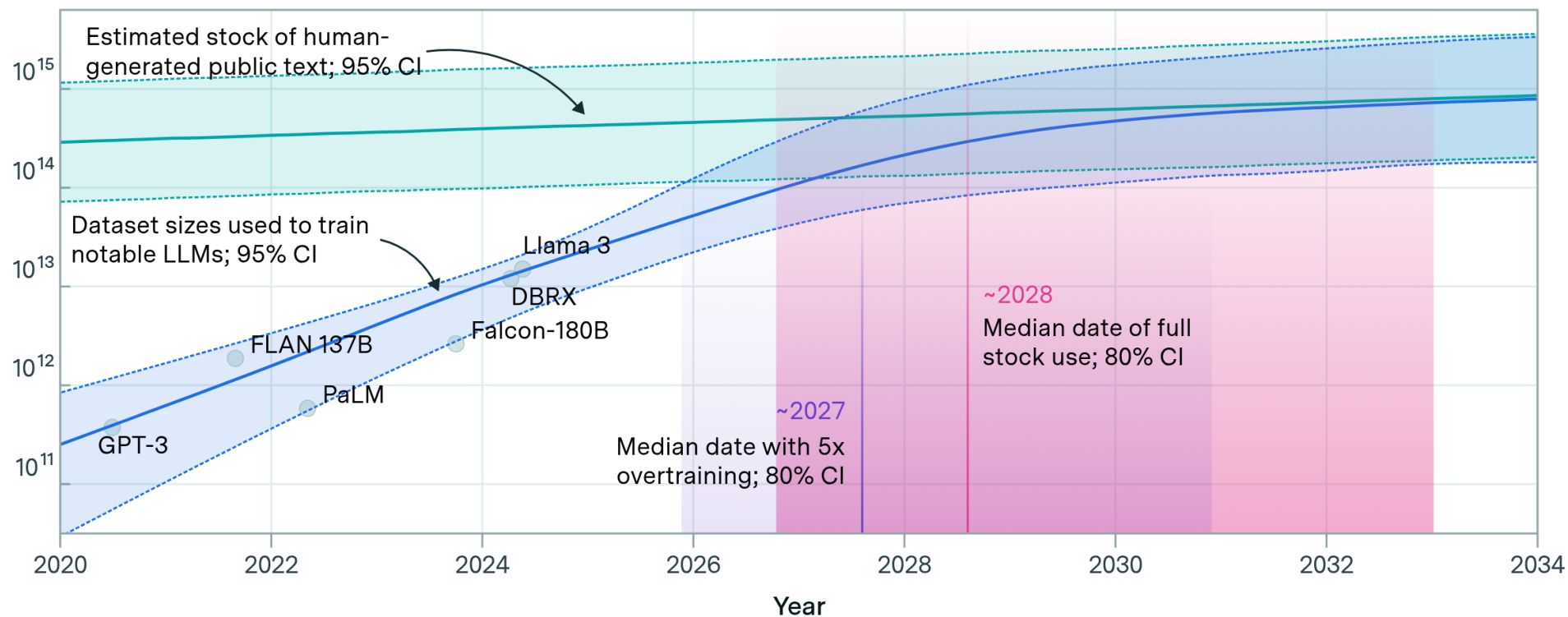
epoch.ai

The Data Usage

Projections of the stock of public text and data usage



Effective stock (number of tokens)



CC-BY

epoch.ai

Comparison between Human and SoTA LMs

Question: Is our AI as strong as humans yet?

	Training Data efficiency	Power Consumption	Adaptation to New Tasks	How to make decision?
Human Brain	< 10B text tokens, a lot of sensory inputs	Learning: ~20W Inference/Thinking: ~20W	Learn with a few examples	By casual relationships and deep understanding
Sota LMs	~10T-50T tokens	Learning: at least @ MWh Inference/Thinking: 1W-30W	Hundreds / Thousands of data points. May fail to generalize	Correlation & Pattern Matching

Estimated #tokens consumed by human in the life time: $70 \text{ years} * 300 \text{ days / year} * 12 \text{ hours / day} * 3600 \text{ seconds / hours} * 10 \text{ tokens / second} = 9.1\text{B}$



Andrej Karpathy ✓

@karpathy



My pleasure to come on Dwarkesh last week, I thought the questions and conversation were really good.

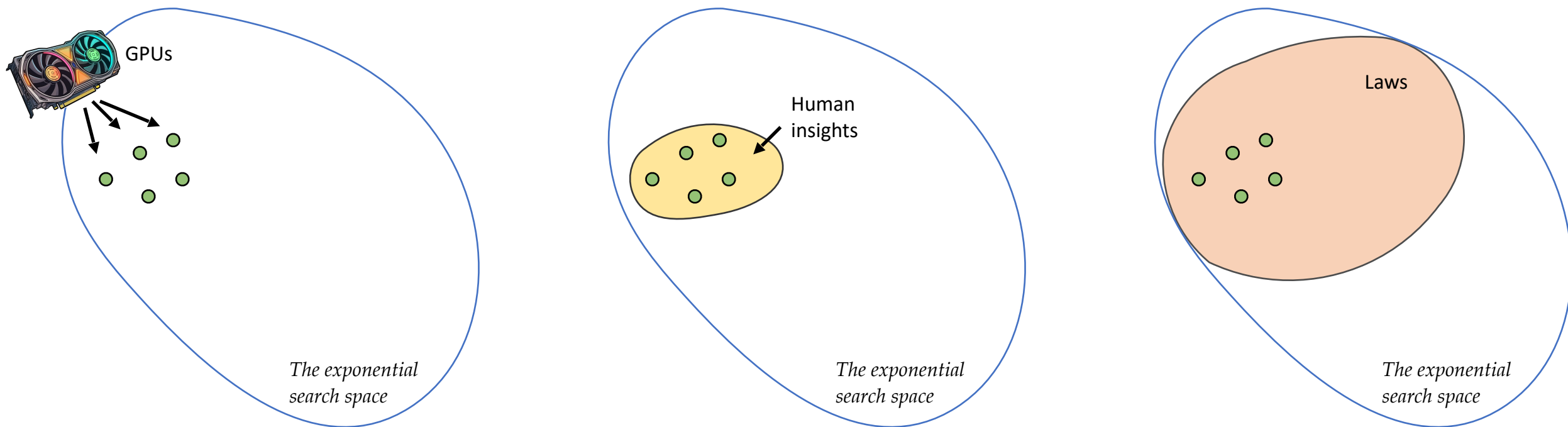
I re-watched the pod just now too. First of all, yes I know, and I'm sorry that I speak so fast :). It's to my detriment because sometimes my speaking thread out-executes my thinking thread, so I think I botched a few explanations due to that, and sometimes I was also nervous that I'm going too much on a tangent or too deep into something relatively spurious. Anyway, a few notes/pointers:

AGI timelines. My comments on AGI timelines looks to be the most trending part of the early response. This is the "decade of agents" is a reference to this earlier tweet [x.com/karpathy/statu...](https://x.com/karpathy/status/1734444444) Basically my AI timelines are about 5-10X pessimistic w.r.t. what you'll find in your neighborhood SF AI house party or on your twitter timeline, but still quite optimistic w.r.t. a rising tide of AI deniers and skeptics. The apparent conflict is not: imo we simultaneously 1) saw a huge amount of progress in recent years with LLMs while 2) there is still a lot of work remaining (grunt work, integration work, sensors and actuators to the physical world, societal work, safety and security work (jailbreaks, poisoning, etc.)) and also research to get done before we have an entity that you'd prefer to hire over a person for an arbitrary job in the world. I think that overall, 10 years should otherwise be a very bullish timeline for AGI, it's only in contrast to present hype that it doesn't feel that way.

How we should do our research from now on?

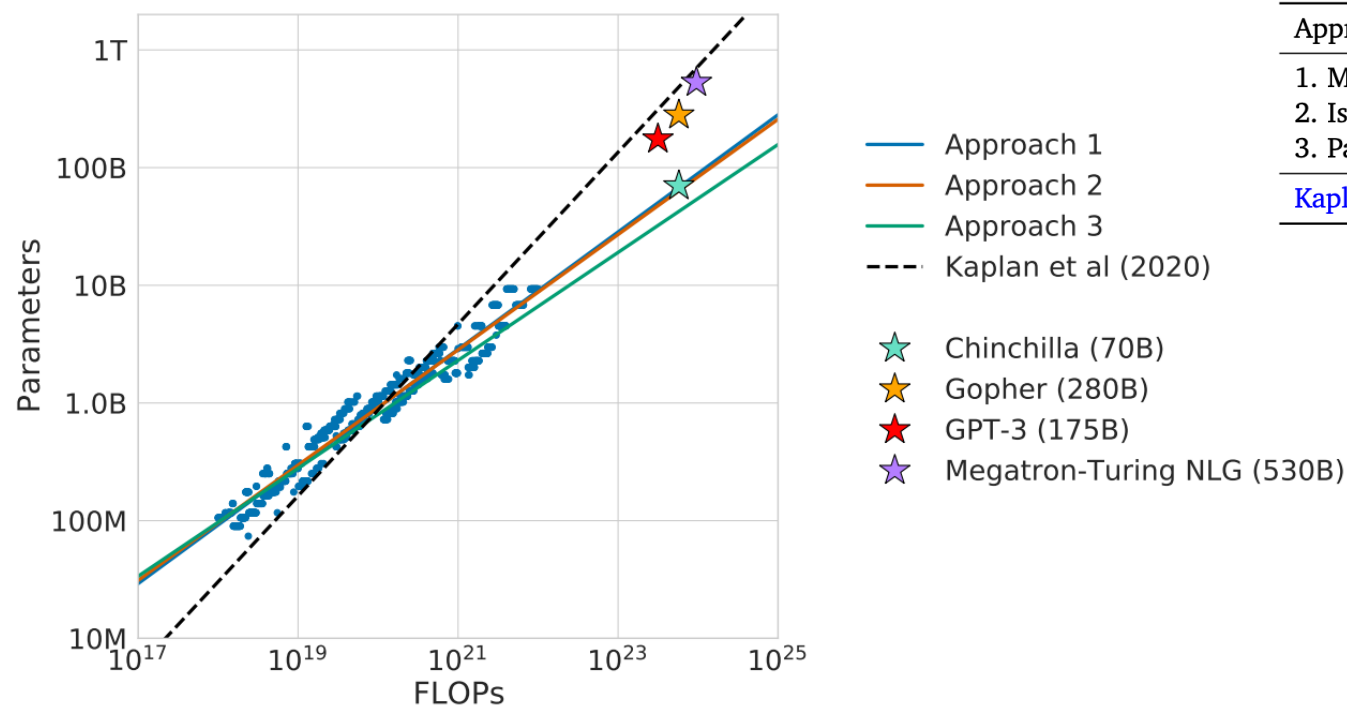
- The “Data Wall problem”
 - We may have used all the available data on the Internet.
 - How to deal with corner cases / personalization / private data?
 - Human is still much more efficient than current AI
- Everyone is GPU poor
 - What are new axes to scale? GPUs are never enough.
 - Data itself cannot extrapolate, only human insights can.

The New (a.k.a. Old) Scaling Axis



Question: Can we **scale** the scaling laws?

How we get Scaling Laws?



Approach	Coeff. a where $N_{opt} \propto C^a$	Coeff. b where $D_{opt} \propto C^b$
1. Minimum over training curves	0.50 (0.488, 0.502)	0.50 (0.501, 0.512)
2. IsoFLOP profiles	0.49 (0.462, 0.534)	0.51 (0.483, 0.529)
3. Parametric modelling of the loss	0.46 (0.454, 0.455)	0.54 (0.542, 0.543)
Kaplan et al. (2020)	0.73	0.27

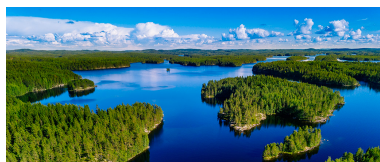
Steps:

1. Collect the experiments
2. Form hypothesis (linear, power-law, etc)
3. Extrapolate

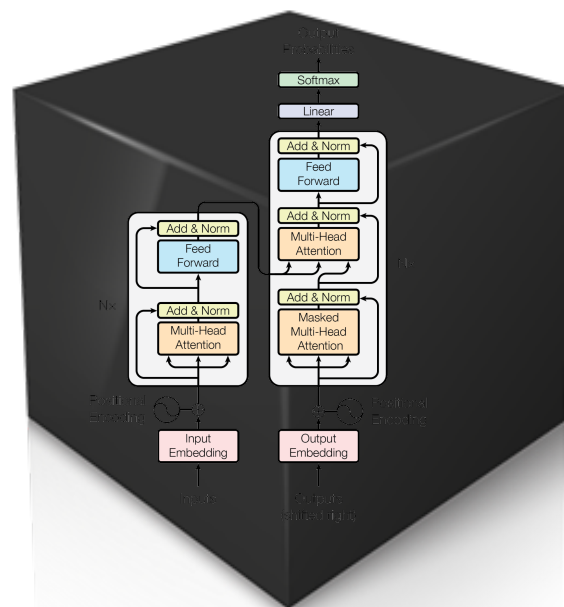
Still pure statistics and need exponential data.
(No leverage of the knowledge of architecture/data)

How does deep learning work?

Input



This is an apple

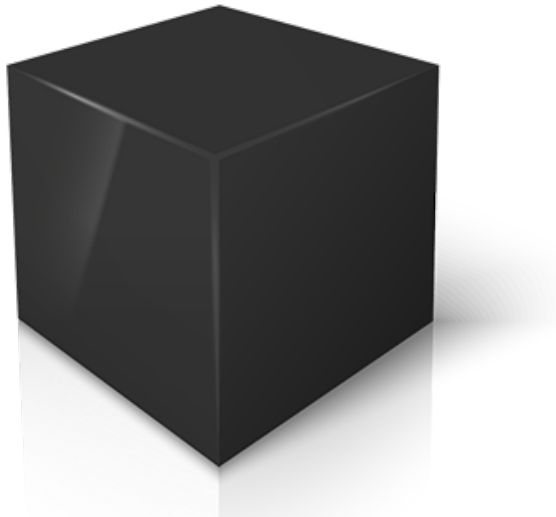


“Some Nonlinear Transformation”

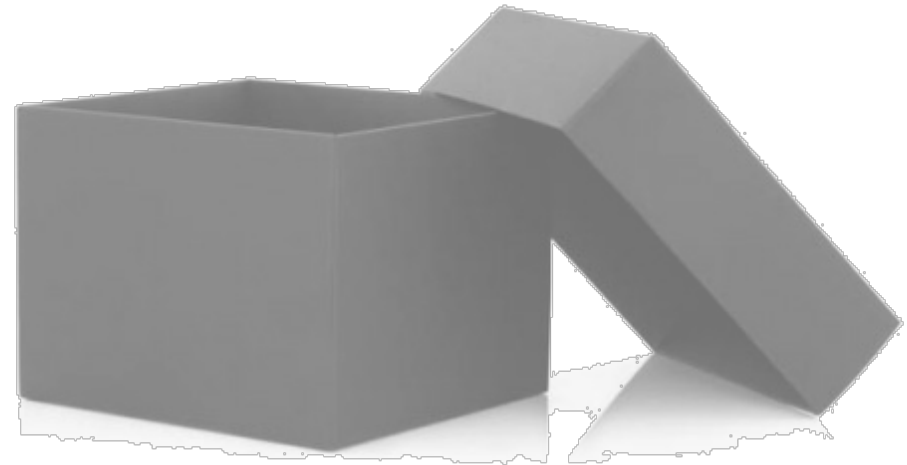


Output

Black-box versus White-box



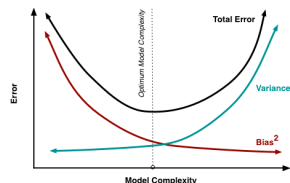
Black box



White box

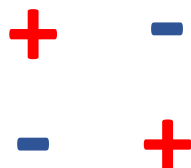
What routes should we take?

Generalization



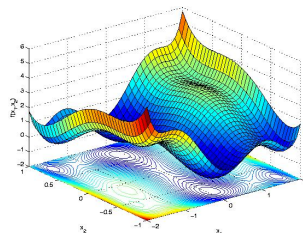
Architecture ✗
training dynamics ✗

Expressibility



Architecture ✓
training dynamics ✗

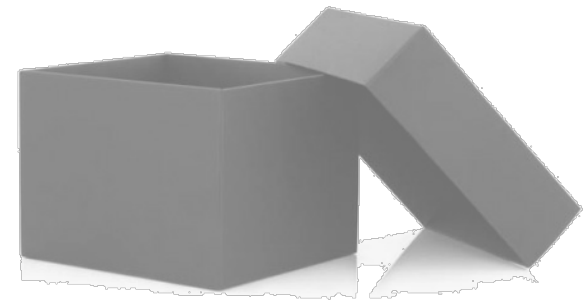
Optimization



Architecture ✗
training dynamics ✓

How about

Architecture ✓
training dynamics ✓



Start From the First Principle

- Training follows Gradient and its variants (SGD, Adams, etc)

$$\dot{\boldsymbol{w}} := \frac{d\boldsymbol{w}}{dt} = - \nabla_{\boldsymbol{w}} J(\boldsymbol{w})$$

- **First principle** → Understand the behavior of the neural networks by checking the gradient **dynamics** induced by the neural **architectures**.
- Sounds complicated.. Is that possible? **Yes**

Architecture ✓
training dynamics ✓

What Gradient Descent gives us?

Short-term:

Finding Simple Structures
(Low-rank, sparsity)

Long-term:

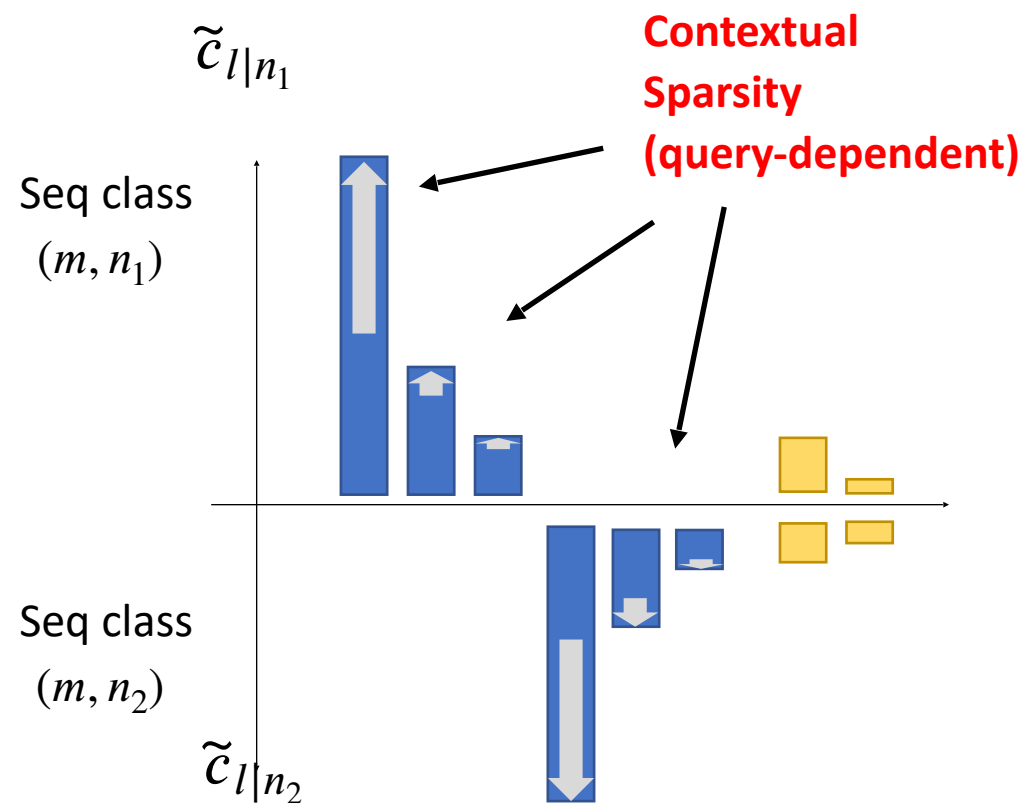
How the representation is learned
(Key to the success of deep models)



Leverage Them in Practical Algorithms

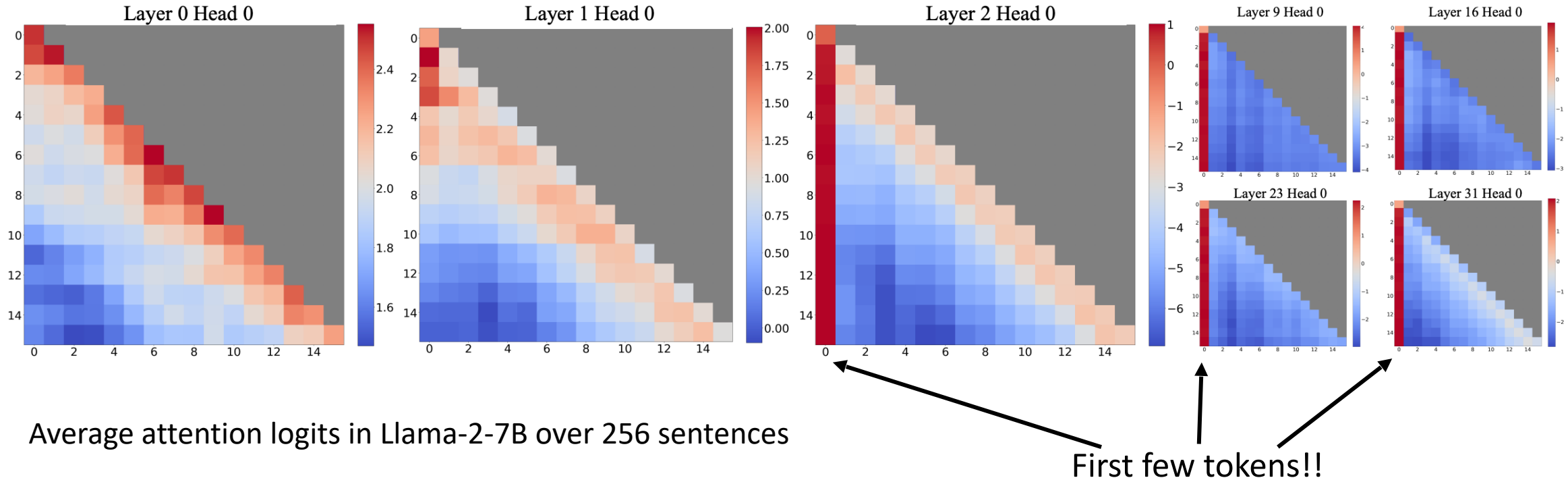
Short-term: Finding Nice Structures

Attention Sparsity



Attention = Learnable TF-IDF (Term Frequency, Inverse Document Frequency)

Attention Sinks: Initial tokens draw a lot of attentions



- Observation: **Initial** tokens have large attention scores, even if they're **not semantically significant**.
- **Attention Sink**: Tokens that disproportionately attract attention irrespective of their relevance.

Understanding Attention Sinks

- **Why?** Attention scores **have to** sum up to **1** for all contextual tokens. (*SoftMax-Off-by-One, Miller et al. 2023*)

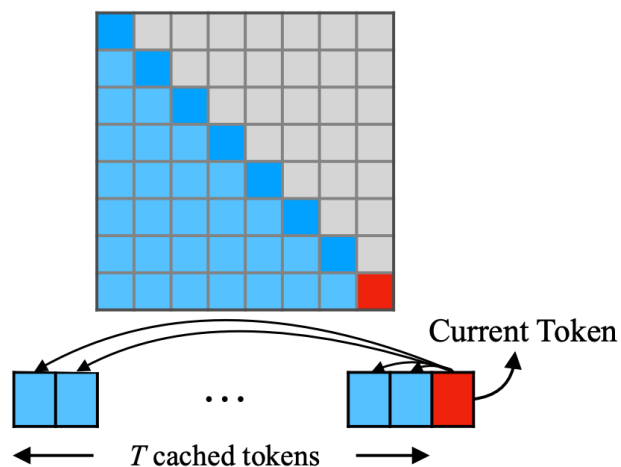
$$\text{SoftMax}(x)_i = \frac{e^{x_i}}{e^{x_1} + \sum_{j=2}^N e^{x_j}}, \quad x_1 \gg x_j, j \in 2, \dots, N$$

- **Why initial tokens?** Their visibility to subsequent tokens, rooted in autoregressive language modeling.
- The model learns a bias towards their **absolute position** rather than the semantics.

Llama-2-13B	PPL (↓)
0+1024 (window)	5158.07
4+1024	5.40
4"\"n"+1020	5.6

StreamingLLM

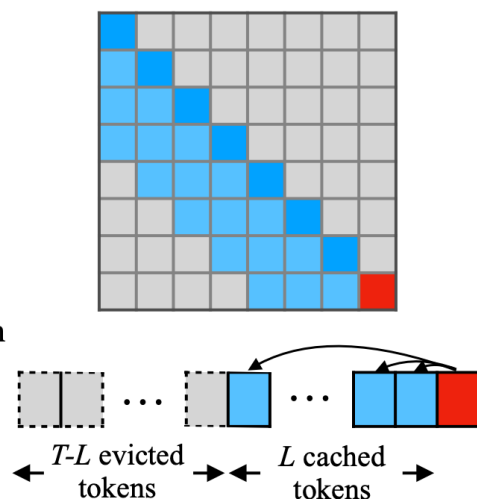
(a) Dense Attention



$O(T^2)$ ✗ PPL: 5641✗

Has poor efficiency and performance on long text.

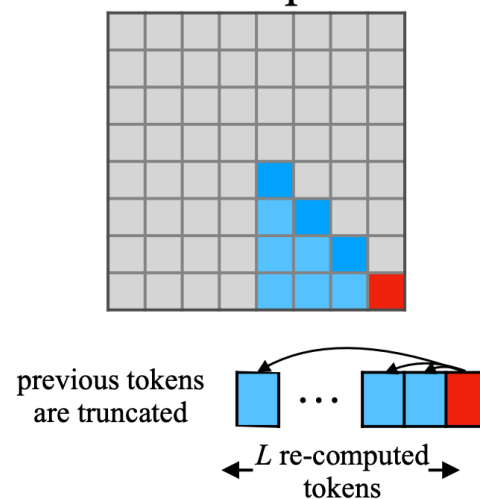
(b) Window Attention



$O(TL)$ ✓ PPL: 5158✗

Breaks when initial tokens are evicted.

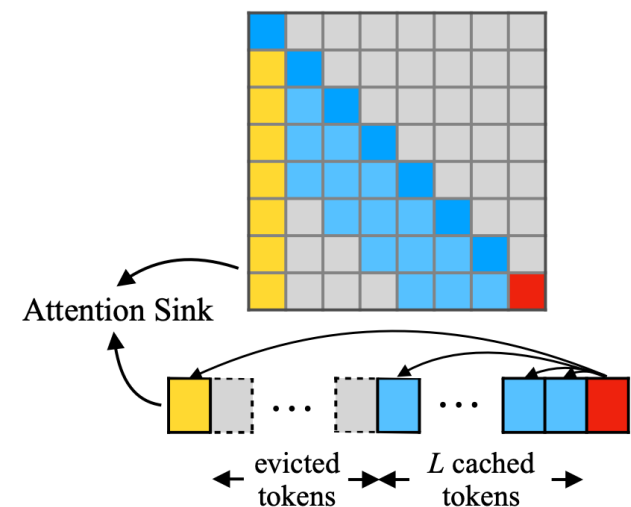
(c) Sliding Window w/ Re-computation



$O(TL^2)$ ✗ PPL: 5.43✓

Has to re-compute cache for each incoming token.

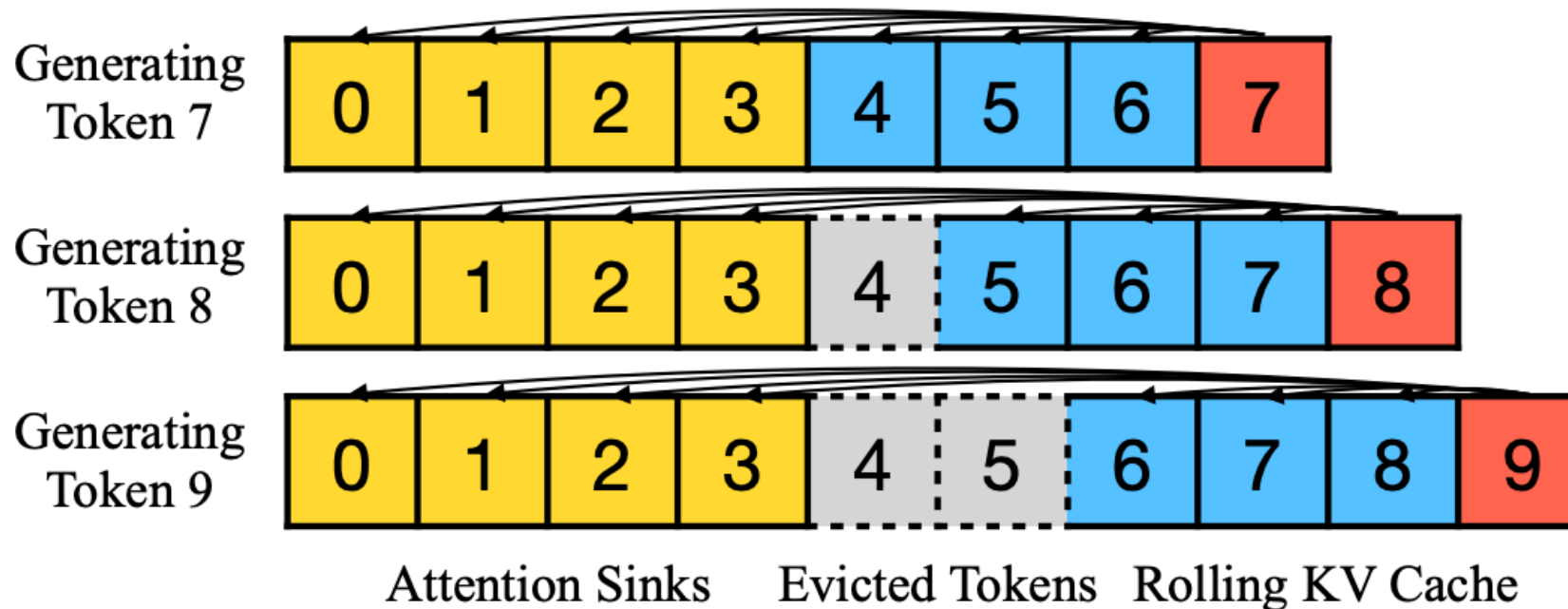
(d) StreamingLLM (ours)



$O(TL)$ ✓ PPL: 5.40✓

Can perform efficient and stable language modeling on long texts.

StreamingLLM



Key design: Position Rolling

For all tokens, use their positions **within cache** to compute positional encoding!

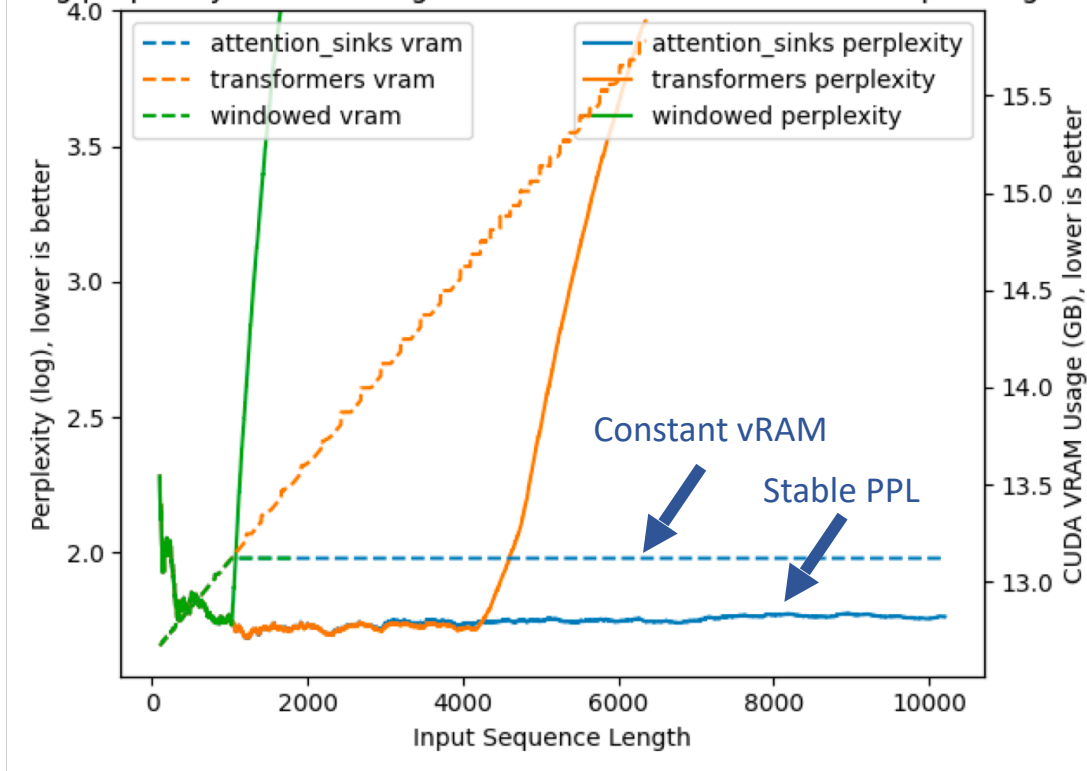
→ Token distance never exceeds pre-trained context window!

StreamingLLM

w/o StreamingLLM	w/ StreamingLLM
<pre>(streaming) guangxuan@l29:~/workspace/streaming-llm\$ CUDA_VISIBLE_DEVICE S=0 python examples/run_streaming_llama.py Loading model from lmsys/vicuna-13b-v1.3 ... Loading checkpoint shards: 67% ██████████ 2/3 [00:09<00:04, 4.94s/it]</pre>	<pre>(streaming) guangxuan@l29:~/workspace/streaming-llm\$ CUDA_VISIBLE_DEVICES=1 py thon examples/run_streaming_llama.py --enable_streaming Loading model from lmsys/vicuna-13b-v1.3 ... Loading checkpoint shards: 67% ██████████ 2/3 [00:09<00:04, 4.89s/it]</pre>

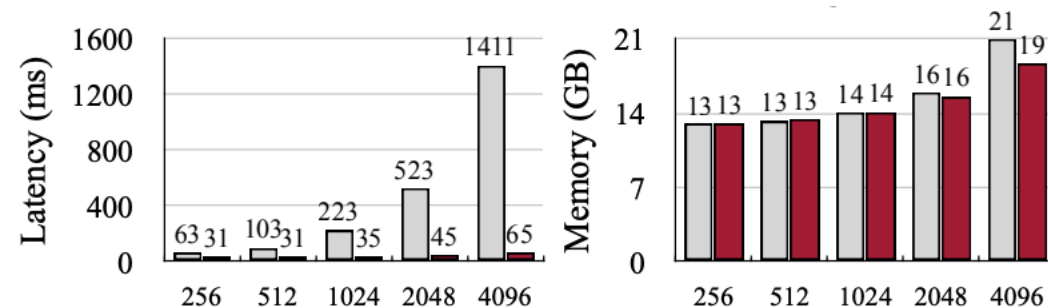
StreamingLLM: stable PPL, constant vRAM

Log perplexity & VRAM usage of Llama 2 7B as a function of input lengths

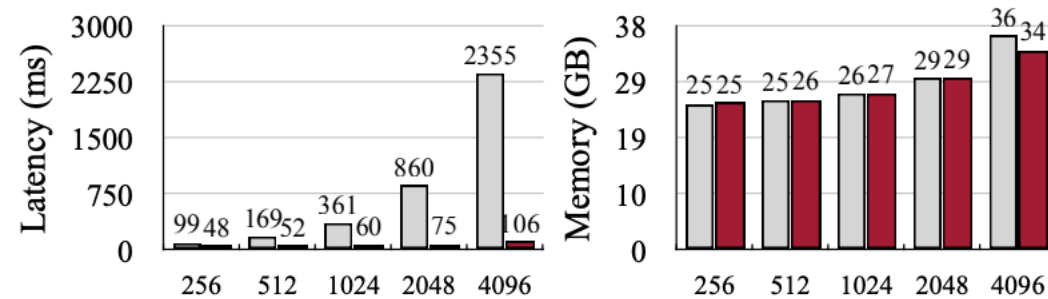


22x faster

Sliding Window with Re-computation
StreamingLLM



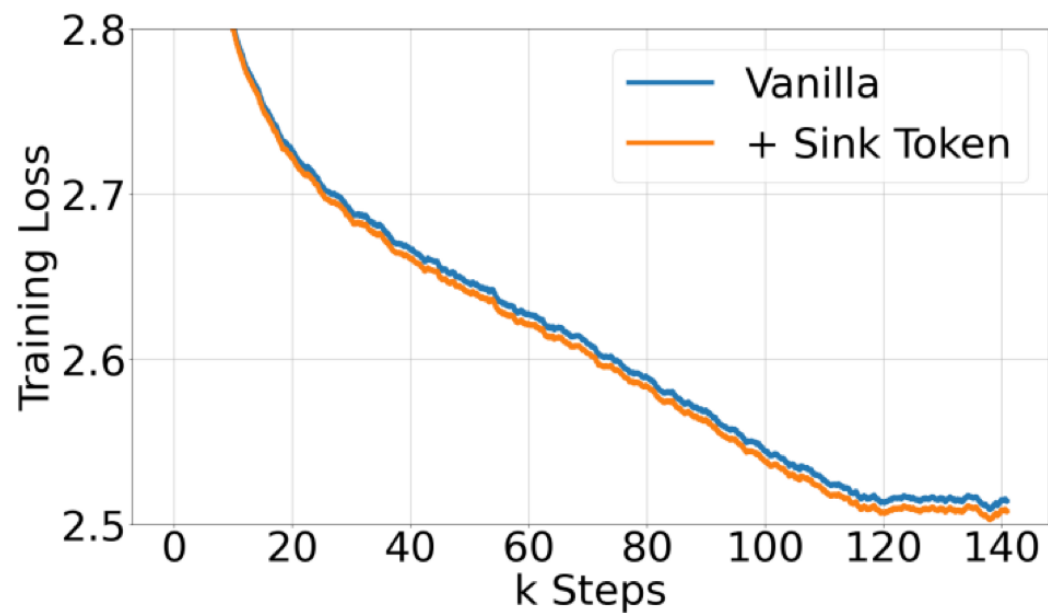
Llama-2-7B



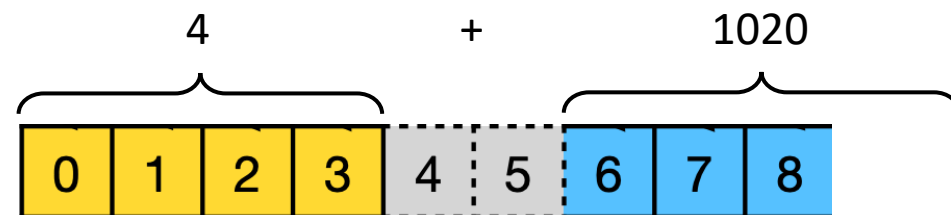
Llama-2-13B

Understanding Attention Sinks

- Pre-train with a Dedicated Attention Sink Token



Cache Config	PPL (↓)			
	0+1024	1+1023	2+1022	4+1020
Vanilla	27.87	18.49	18.05	18.05
Zero Sink	29214	19.90	18.27	18.01
Learnable Sink	1235	18.01	18.01	18.02

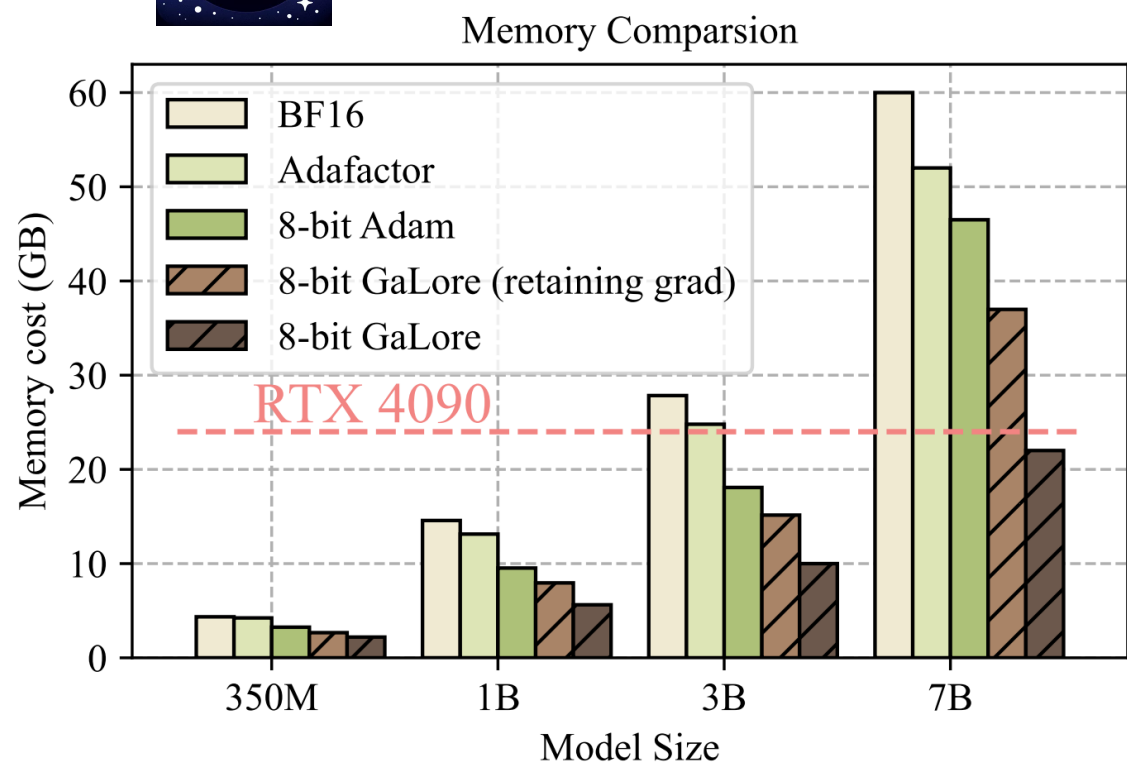


Impact

Attention: Following GPT-3, attention blocks alternate between banded window and fully dense patterns [8][9], where the bandwidth is 128 tokens. Each layer has 64 query heads of dimension 64, and uses Grouped Query Attention (GQA [10][11]) with 8 key-value heads. We apply rotary position embeddings [12] and extend the context length of dense layers to 131,072 tokens using YaRN [13]. Each attention head has a learned bias in the denominator of the softmax, similar to off-by-one attention and attention sinks [14][15], which enables the attention mechanism to pay no attention to any tokens.

- 900+ citations
- Used in GPT OSS models in pre-training

GaLore: Pre-training 7B model on RTX 4090 (24G)



	Rank	Retain grad	Memory	Token/s
8-bit AdamW		Yes	40GB	1434
8-bit GaLore	16	Yes	28GB	1532
8-bit GaLore	128	Yes	29GB	1532
16-bit GaLore	128	Yes	30GB	1615
16-bit GaLore	128	No	18GB	1587
8-bit GaLore	1024	Yes	36GB	1238

* SVD takes around 10min for 7B model, but runs every T=500-1000 steps.

Third-party evaluation by @llamafactory_ai



Memory Saving with GaLore

Algorithm 1: GaLore, PyTorch-like

```
for weight in model.parameters():
    grad = weight.grad
    # original space -> compact space
    lor_grad = project(grad)
    # update by Adam, Adafactor, etc.
    lor_update = update(lor_grad)
    # compact space -> original space
    update = project_back(lor_update)
    weight.data += update
```

GaLore

$$\begin{aligned} G_t &\leftarrow -\nabla_W \phi(W_t) \\ \text{If } t \% T == 0: & \\ &\text{Compute } P_t = \text{SVD}(G_t) \in \mathbb{R}^{m \times r} \\ R_t &\leftarrow P_t^T G_t \quad \{\text{project}\} \\ \tilde{R}_t &\leftarrow \rho(R_t) \quad \{\text{Adam in low-rank}\} \\ \tilde{G}_t &\leftarrow P_t \tilde{R}_t \quad \{\text{project-back}\} \\ W_{t+1} &\leftarrow W_t + \eta \tilde{G}_t \end{aligned}$$

Memory Usage	Weight	Optim States	Projection	Total
Full-rank	mn	$2mn$	0	$3mn$
Low-rank adaptor	$mn+mr+nr$	$2mr+2nr$	0	$2mn+3mr+3nr$
GaLore	mn	$mr+2nr$	mr	$mn+2mr+2nr$

$\uparrow$
 W_t

$\uparrow$
 R_t

$\uparrow$
 P_t

Pre-training Results (LLaMA 7B)

Params	Hidden	Intermediate	Heads	Layers	Steps	Data amount
60M	512	1376	8	8	10K	1.3 B
130M	768	2048	12	12	20K	2.6 B
350M	1024	2736	16	24	60K	7.8 B
1 B	2048	5461	24	32	100K	13.1 B
7 B	4096	11008	32	32	150K	19.7 B

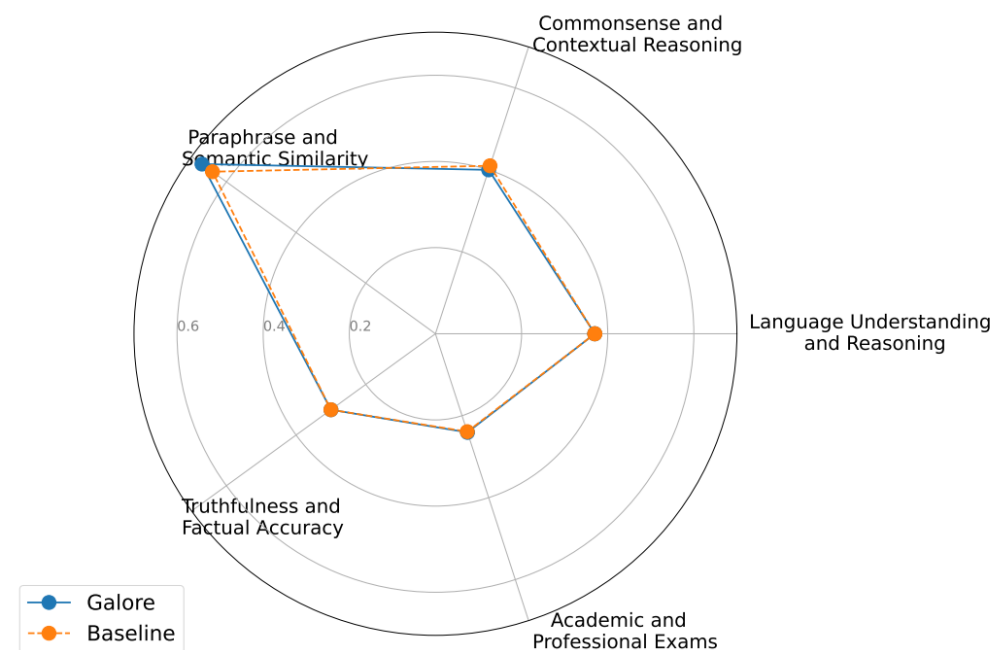
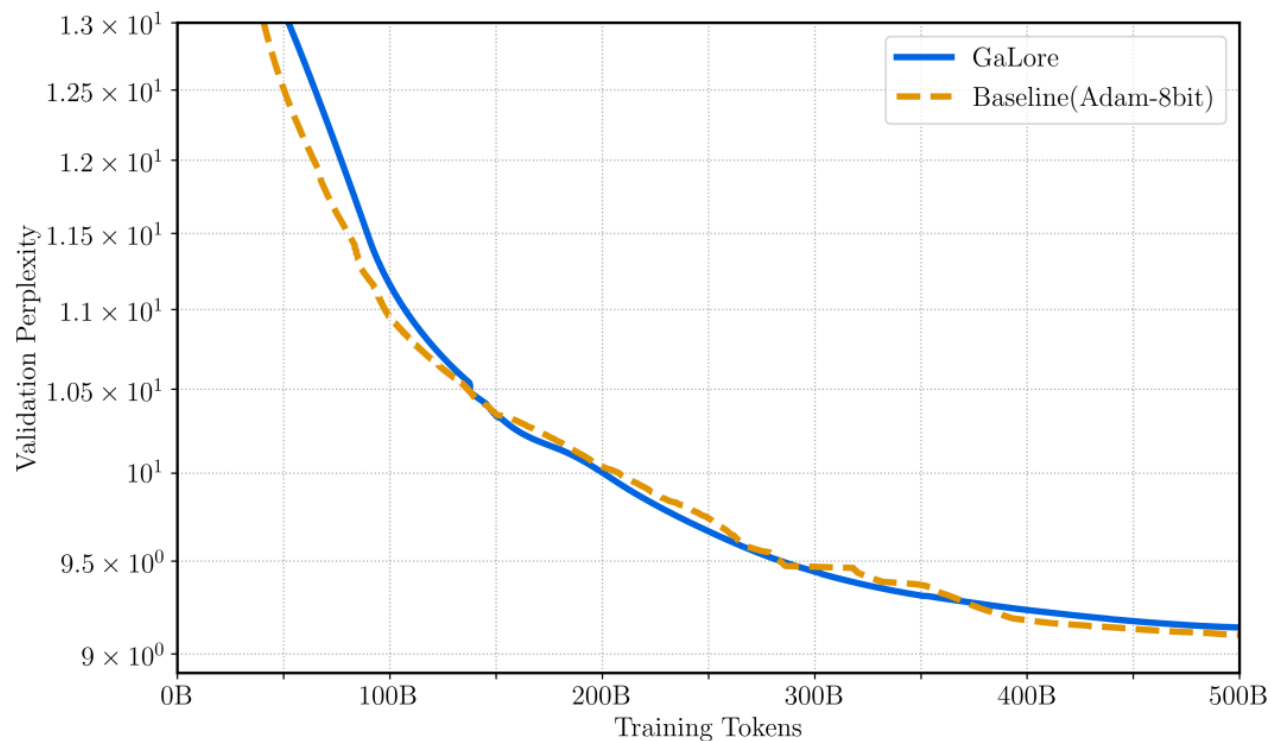
	Mem	40K	80K	120K	150K
 8-bit GaLore	18G	17.94	15.39	14.95	14.65
8-bit Adam	26G	18.09	15.47	14.83	14.61
Tokens (B)		5.2	10.5	15.7	19.7

* Experiments are conducted on 8 x 8 A100

	60M	130M	350M	1B
Full-Rank	34.06 (0.36G)	25.08 (0.76G)	18.80 (2.06G)	15.56 (7.80G)
GaLore	34.88 (0.24G)	25.36 (0.52G)	18.95 (1.22G)	15.64 (4.38G)
Low-Rank	78.18 (0.26G)	45.51 (0.54G)	37.41 (1.08G)	142.53 (3.57G)
LoRA	34.99 (0.36G)	33.92 (0.80G)	25.58 (1.76G)	19.21 (6.17G)
ReLoRA	37.04 (0.36G)	29.37 (0.80G)	29.08 (1.76G)	18.33 (6.17G)
r/d_{model}	128 / 256	256 / 768	256 / 1024	512 / 2048
Training Tokens	1.1B	2.2B	6.4B	13.1B

* On LLaMA 1B, ppl is better (~14.97) with ½ rank (1024/2048)

Pre-training Results (LLaMA 7B)



Long-term: How Network finds Representation

Type of Representations

Representation

(Traditional) Symbolic
representation

Neural
Representation

$$\nabla \cdot \mathbf{E} = \frac{\rho_v}{\epsilon}$$

(Gauss' Law)

$$\nabla \cdot \mathbf{H} = 0$$

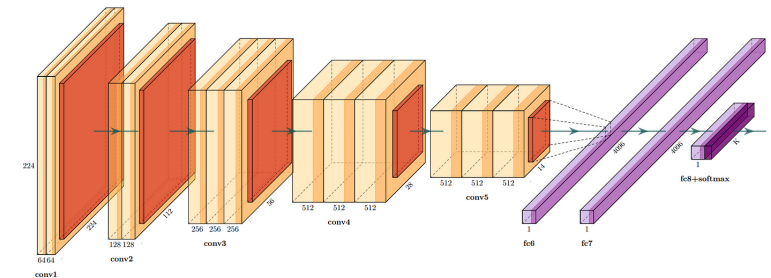
(Gauss' Law for Magnetism)

$$\nabla \times \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial t}$$

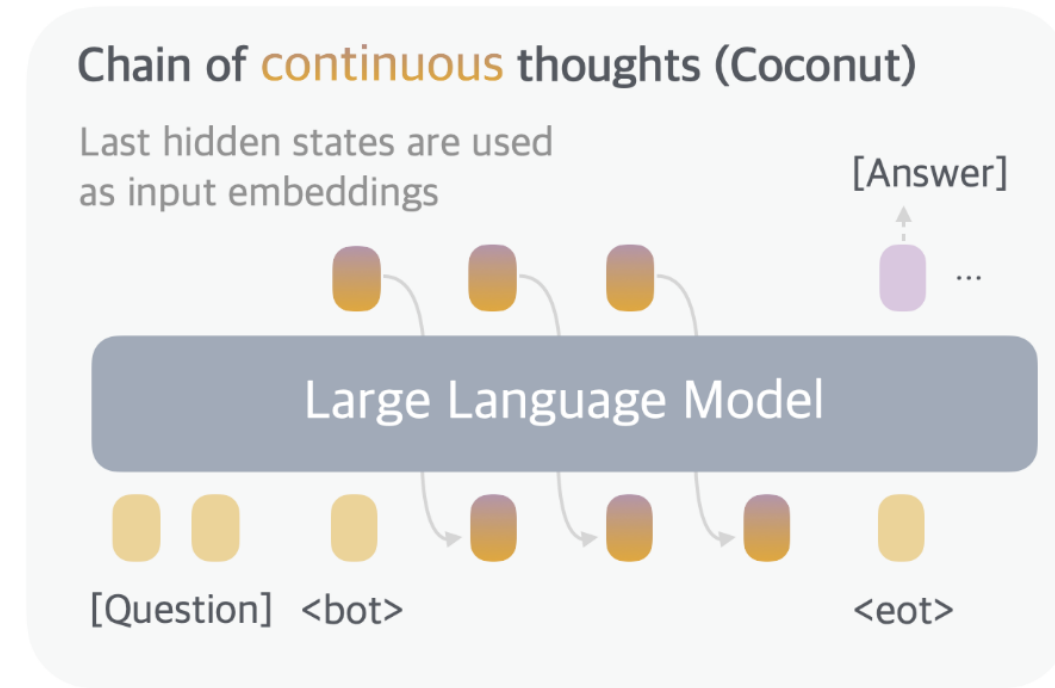
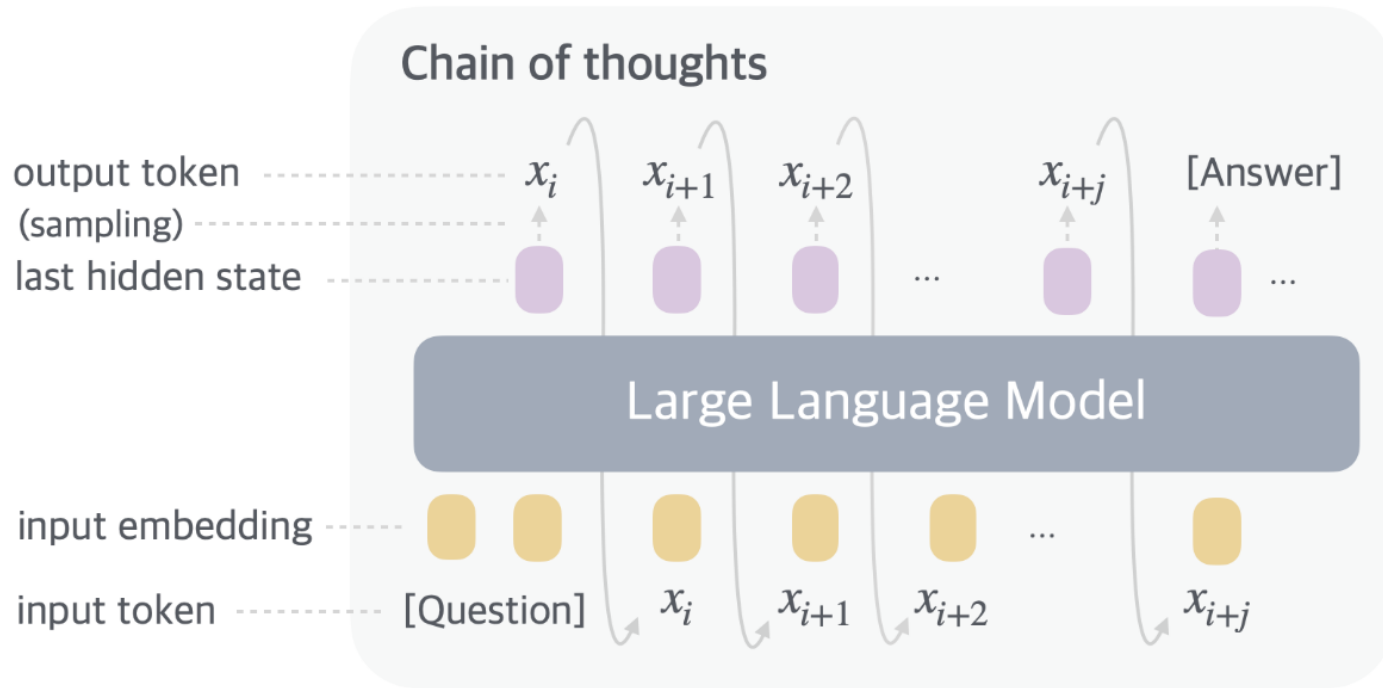
(Faraday's Law)

$$\nabla \times \mathbf{H} = \mathbf{J} + \epsilon \frac{\partial \mathbf{E}}{\partial t}$$

(Ampere's Law)



CoConut (Chain of Continuous Thought)



How to train Coconut?

Language CoT
(training data)

[Question] [Step 1] [Step 2] [Step 3] ... [Step N] [Answer]

[Thought] : continuous thought

[...] : sequence of tokens

<...> : special token

... : calculating loss

Stage 0

[Question] <bot> <eot> [Step 1] [Step 2] ... [Step N] [Answer]

Stage 1

[Question] <bot> [Thought] <eot> [Step 2] [Step 3] ... [Step N] [Answer]

Stage 2

[Question] <bot> [Thought] [Thought] <eot> [Step 3] ... [Step N] [Answer]

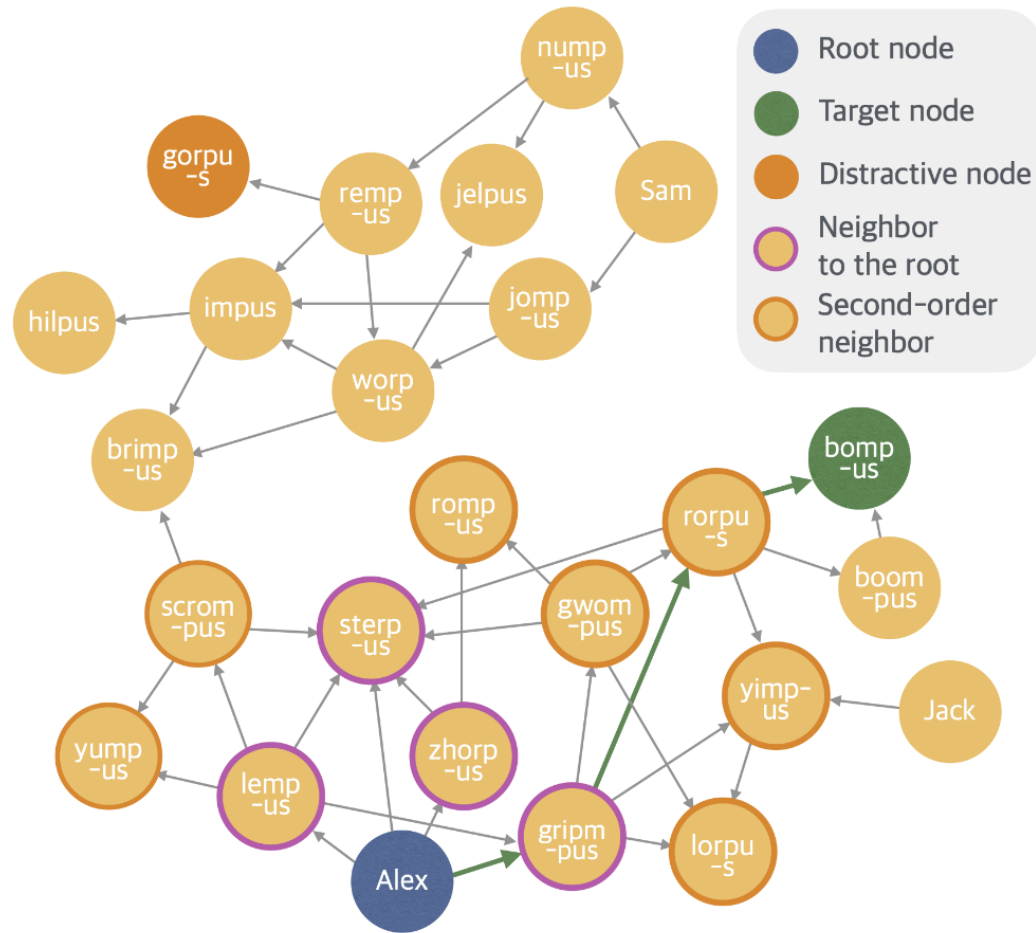
...

...

Stage N

[Question] <bot> [Thought] [Thought] ... [Thought] <eot> [Answer]

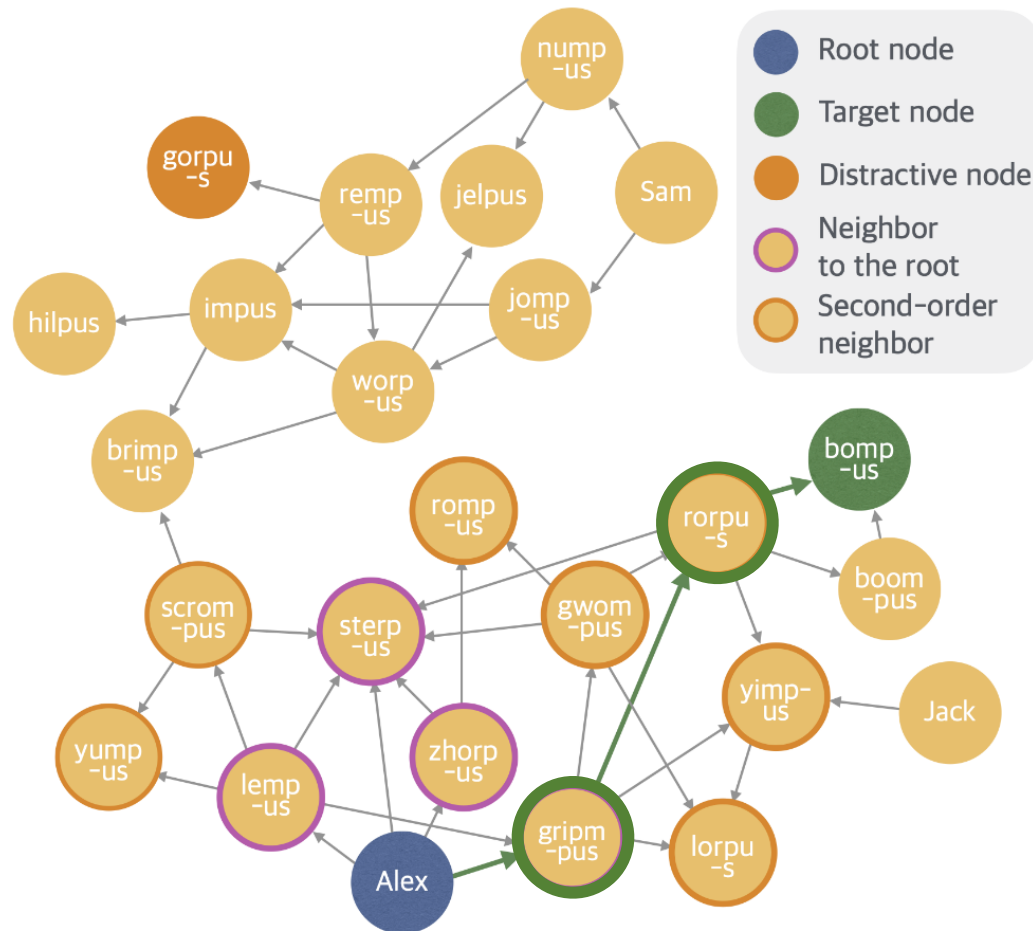
Interpreting the embeddings



Question:

Every jells is a worpus. Sam is a jumpus. Every gwompus is a rompus. ... Every lumps is a yumpus. Question: **Is Alex a gorpus or bompus?**

Ground Truth Solutions



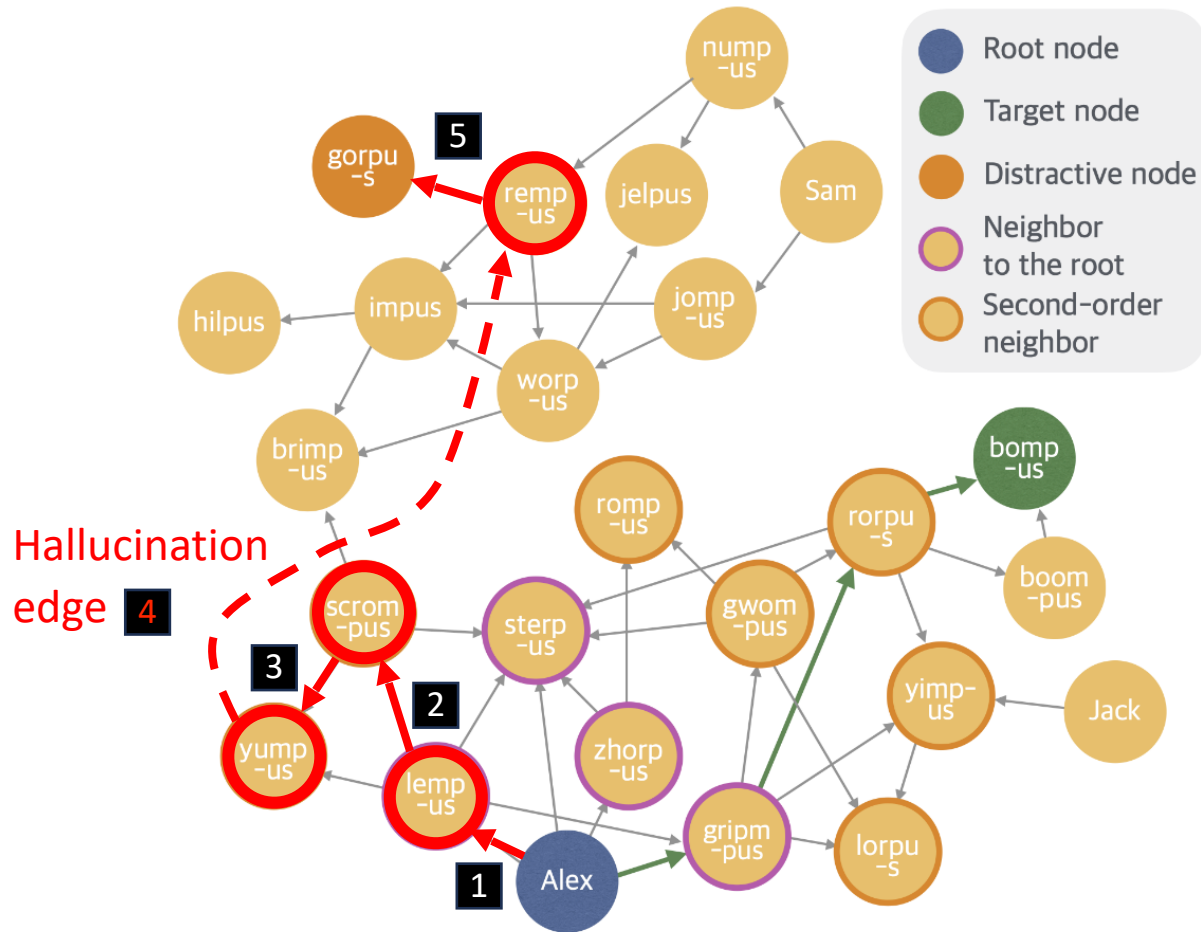
Question:

Every jells is a worpus. Sam is a jumpus. Every gwompus is a rompus. ... Every lumps is a yumpus. Question: **Is Alex a gorpus or bompus?**

Ground Truth Solution

Alex is a grimpus.
Every grimpus is a rorpus.
Every rorpus is a bompus.
Alex is a bompus

Chain of thoughts lead to hallucinations



Question:

Every jells is a worpus. Sam is a jumpus. Every gwompus is a rompus. ... Every lumpus is a yumpus. Question: **Is Alex a gorpus or bompus?**

Ground Truth Solution

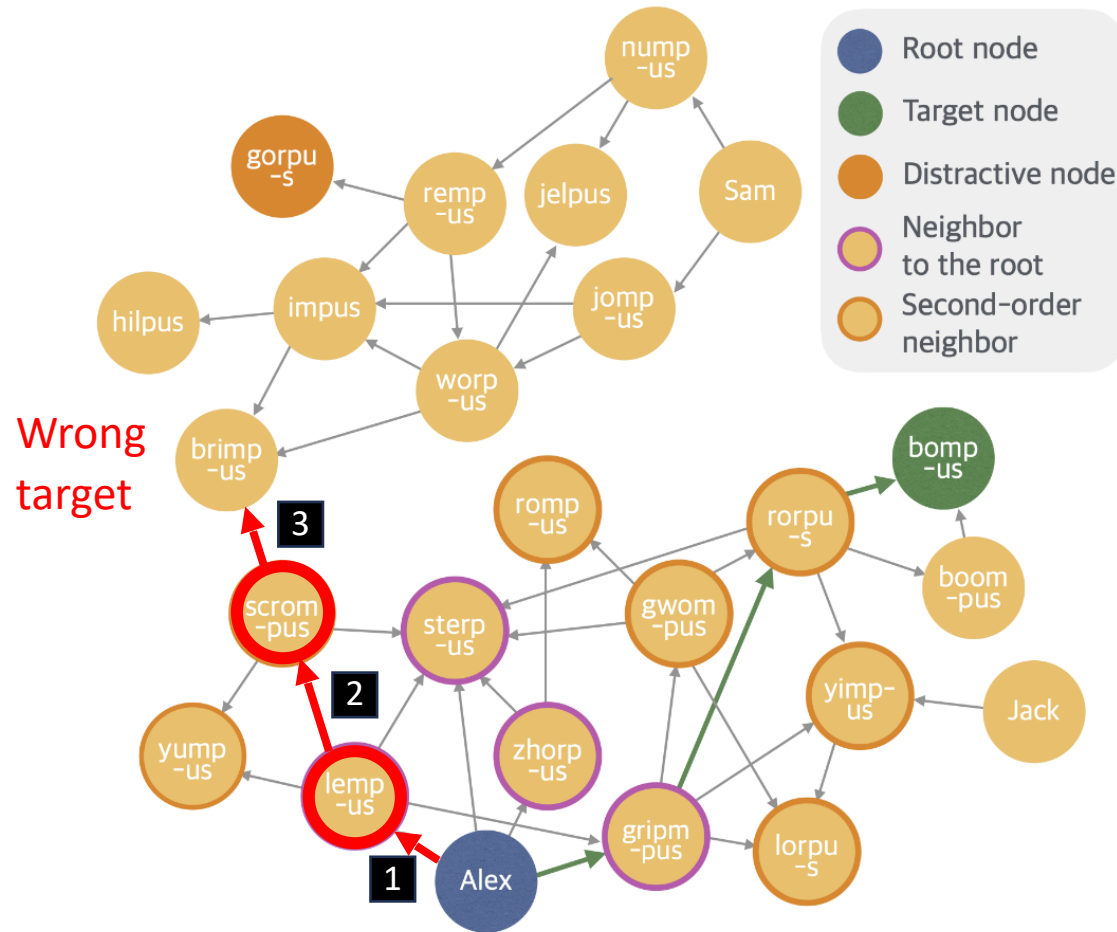
Alex is a grimpus.
Every grimpus is a rorpus.
Every rorpus is a bompus.
Alex is a bompus

CoT

Alex is a lempus. 1
Every lempus is a scrompus. 2
Every scrompus is a yumpus. 3
Every yumpus is a rempus. 4
Every rempus is a gorpus. 5
Alex is a gorpus ✗

(Hallucination)

Continuous Thoughts



Question:

Every jells is a worpus. Sam is a jumpus. Every gwompus is a rompus. ... Every lumps is a yumpus. Question: **Is Alex a gorpus or bompus?**

Ground Truth Solution

Alex is a grimpus.
Every grimpus is a rorpus.
Every rorpus is a bompus.
Alex is a bompus

CoT

Alex is a lempus.
Every lempus is a scrompus.
Every scrompus is a yumpus.
Every yumpus is a rempus.
Every rempus is a gorpus.
Alex is a gorpus ✗

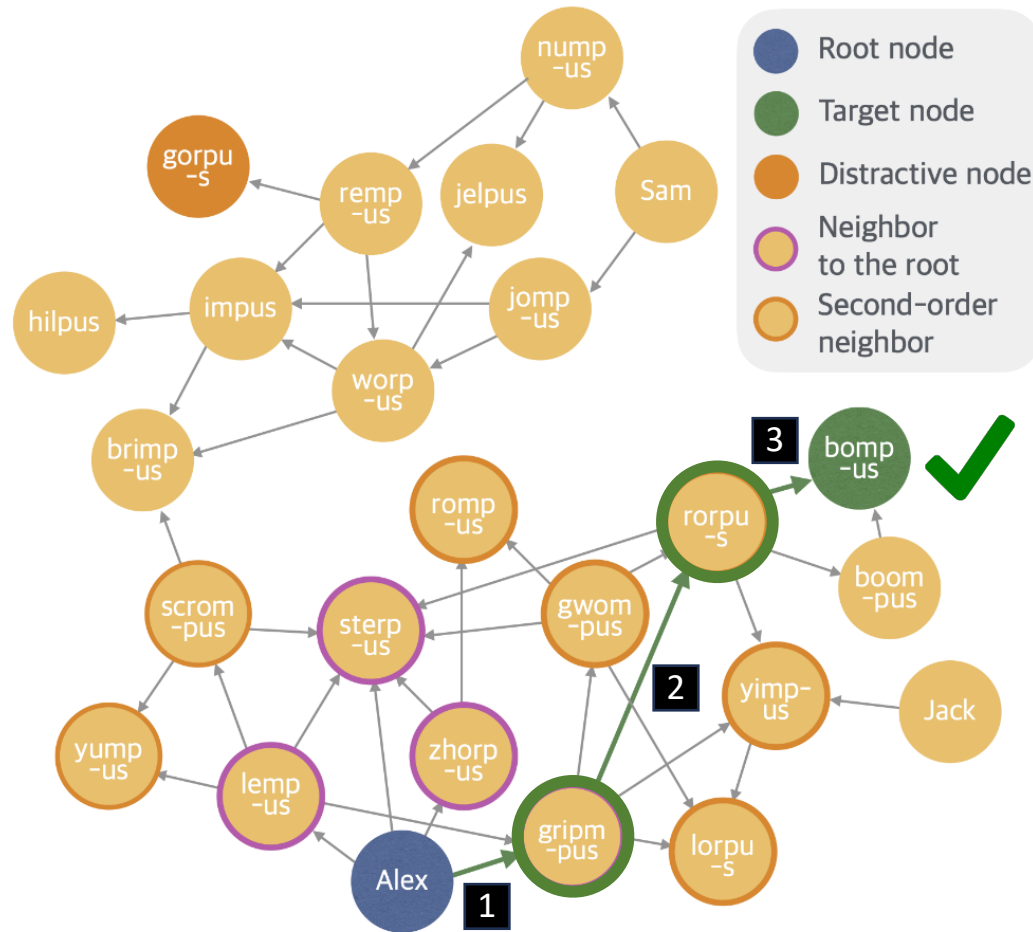
(Hallucination)

Ours (k=1)

<bot> [Thought] <eot>
Every lempus is a scrompus.
Every scrompus is a brimpus.
Alex is a brimpus ✗

(Wrong Target)

Two-step Continuous Thought works!



Question:

Every jells is a worpus. Sam is a jumpus. Every gwompus is a rompus. ... Every lumps is a yumpus. Question: **Is Alex a gorpus or bompus?**

Ground Truth Solution

Alex is a grimpus.
Every grimpus is a rorpus.
Every rorpus is a bompus.
Alex is a bompus

Ours (k=1)

<bot> [Thought] <eot>
Every lempus is a scrompus.
Every scrompus is a brimpus.
Alex is a brimpus ✗

(Wrong Target)

CoT

Alex is a lempus.
Every lempus is a scrompus.
Every scrompus is a yumpus.
Every yumpus is a rempus.
Every rempus is a gorpus.
Alex is a gorpus ✗

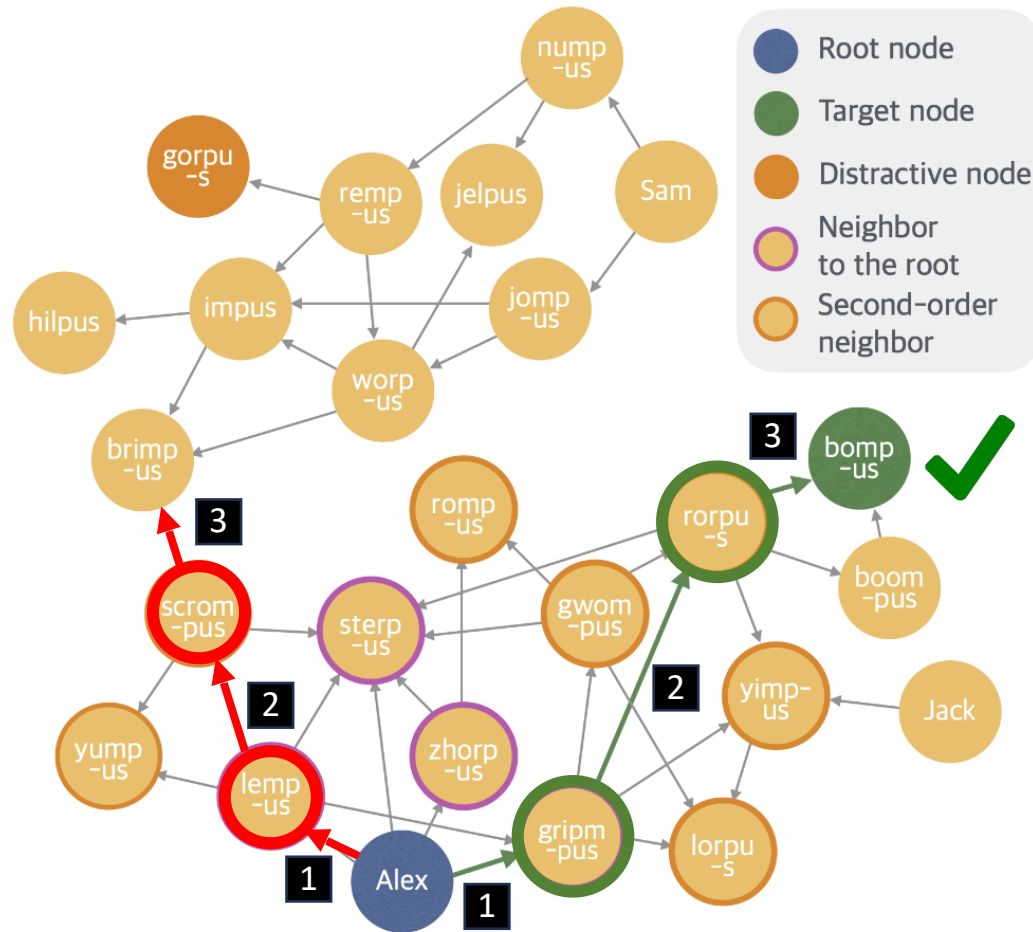
(Hallucination)

Ours (k=2)

<bot> [thought] [thought] <eot>
Every rorpus is a bompus.
Alex is a bompus ✓

(Correct Path)

Two-step Continuous Thought works!



Ours (k=1) **1**

<bot> [Thought] <eot>
Every lempus is a scrompus.
Every scrompus is a brimpus.
Alex is a brimpus ✗

(Wrong Target)

Ours (k=2) **1** **2**

<bot> [thought] [thought] <eot>
Every rorpus is a bompus.
Alex is a bompus ✓

(Correct Path)

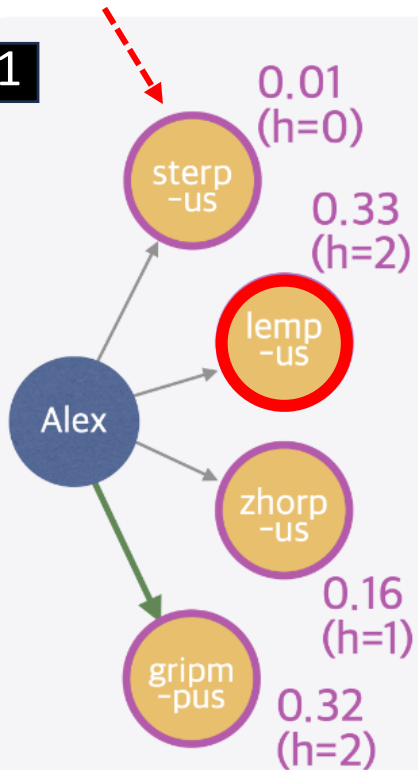
Why the same continuous thoughts **1** lead to different path?!

What's inside?

Let's probe!

Dead-end

1



Coconut (k=1)

<bot> [Thought] <eot>
Every lempus ...

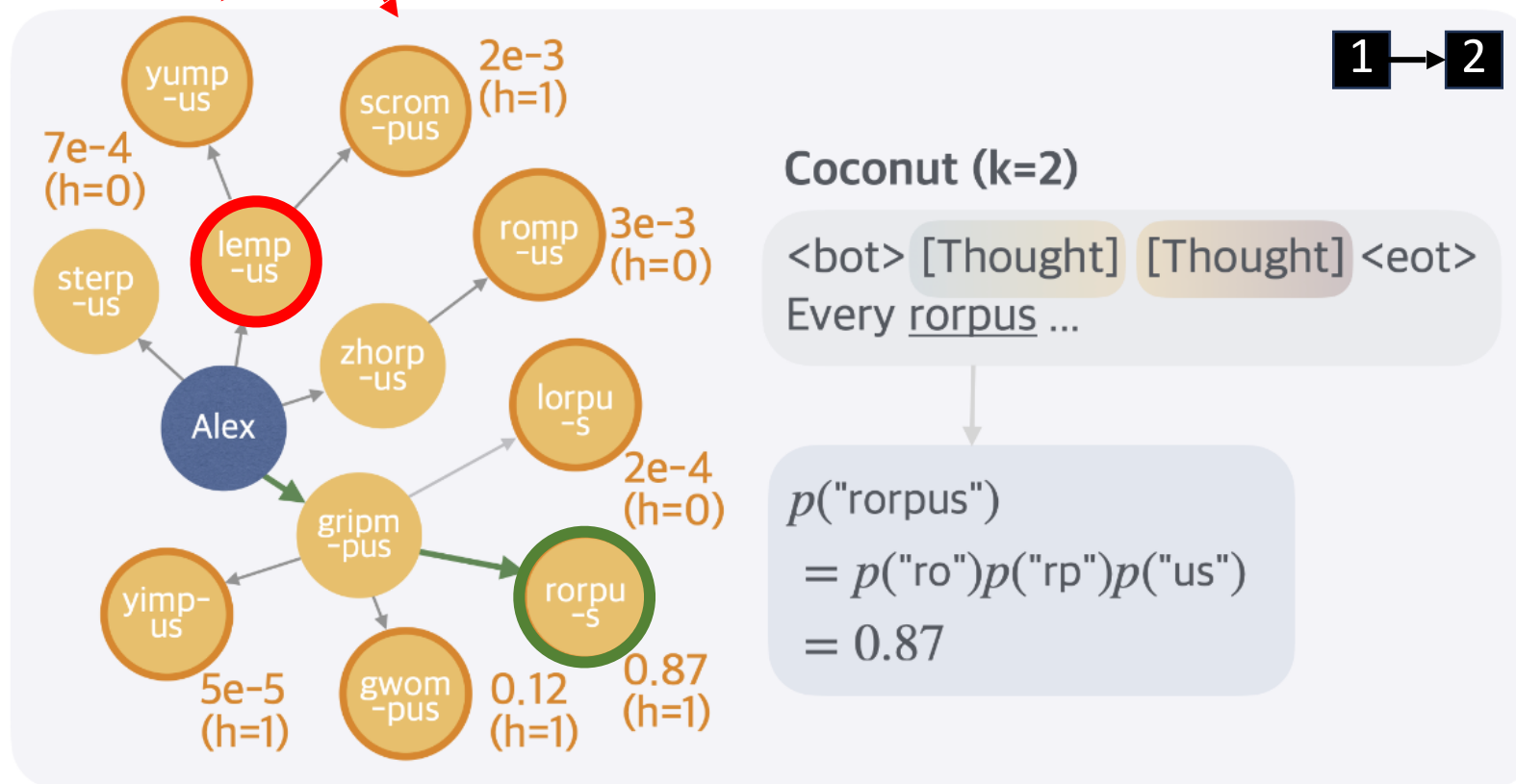
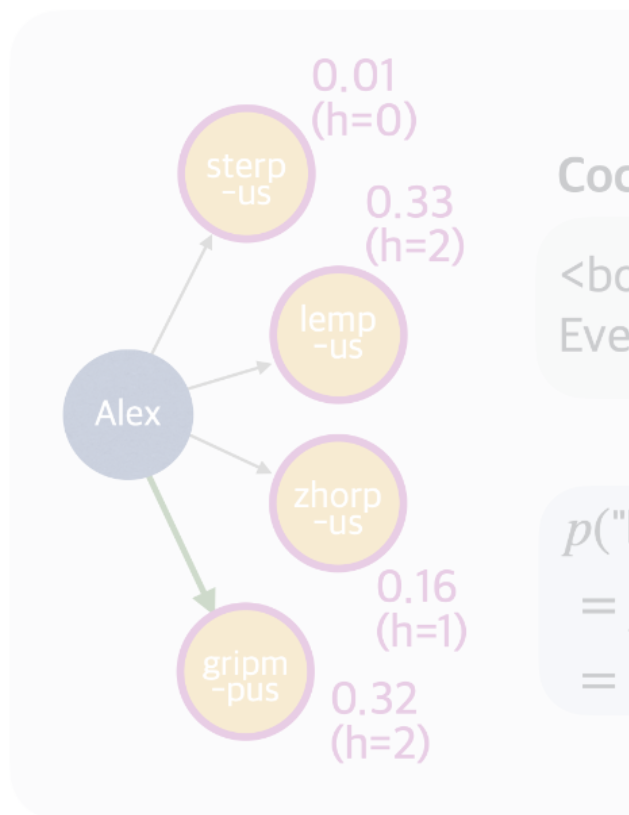
$$\begin{aligned} p(\text{"lempus"}) \\ &= p(\text{"le"})p(\text{"mp"})p(\text{"us"}) \\ &= 0.33 \end{aligned}$$

"lempus" is not on the right path but for step=1, it is the **most promising**

What's inside?

Promising node → dead-end

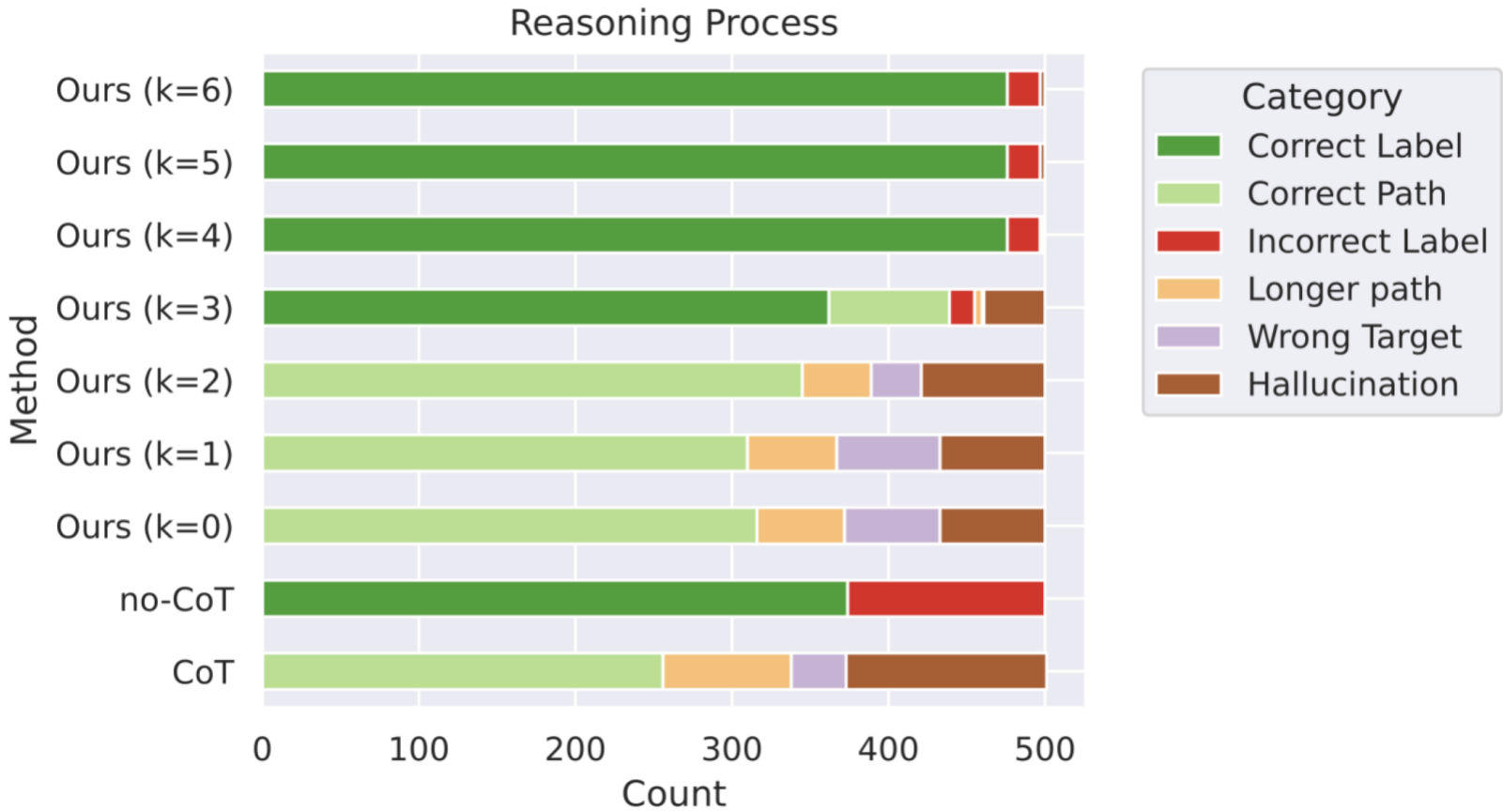
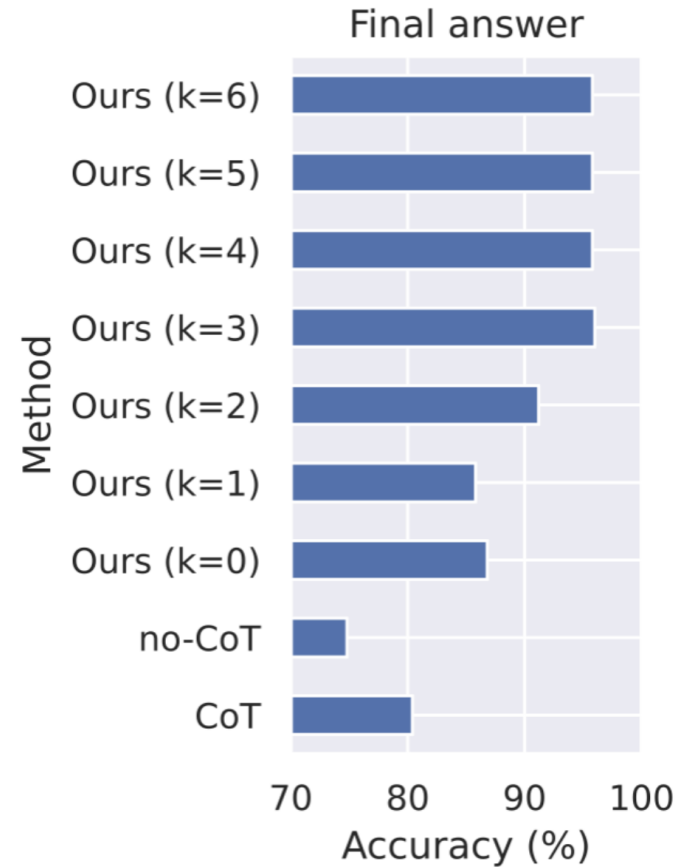
Interestingly, it encodes all possible paths!



Performance in ProsQA

Dataset	Training	Validation	Test
GSM8k	385,620	500	1319
ProntoQA	9,000	200	800
ProsQA	17,886	300	500

# Nodes	# Edges	Len. of Shortest Path	# Shortest Paths
23.0	36.0	3.8	1.6



CoConut

Method	GSM8k		ProntoQA		ProsQA	
	Acc. (%)	# Tokens	Acc. (%)	# Tokens	Acc. (%)	# Tokens
CoT	42.9 $\pm$ 0.2	25.0	98.8 $\pm$ 0.8	92.5	77.5 $\pm$ 1.9	49.4
No-CoT	16.5 $\pm$ 0.5	2.2	93.8 $\pm$ 0.7	3.0	76.7 $\pm$ 1.0	8.2
iCoT	30.0*	2.2	99.8 $\pm$ 0.3	3.0	98.2 $\pm$ 0.3	8.2
Pause Token	16.4 $\pm$ 1.8	2.2	77.7 $\pm$ 21.0	3.0	75.9 $\pm$ 0.7	8.2
CoCONUT (Ours)	34.1 $\pm$ 1.5	8.2	99.8 $\pm$ 0.2	9.0	97.0 $\pm$ 0.3	14.2
- <i>w/o curriculum</i>	14.4 $\pm$ 0.8	8.2	52.4 $\pm$ 0.4	9.0	76.1 $\pm$ 0.2	14.2
- <i>w/o thought</i>	21.6 $\pm$ 0.5	2.3	99.9 $\pm$ 0.1	3.0	95.5 $\pm$ 1.1	8.2
- <i>pause as thought</i>	24.1 $\pm$ 0.7	2.2	100.0 $\pm$ 0.1	3.0	96.6 $\pm$ 0.8	8.2

Better performance than No-CoT
Shorter thinking process than CoT

CoConut

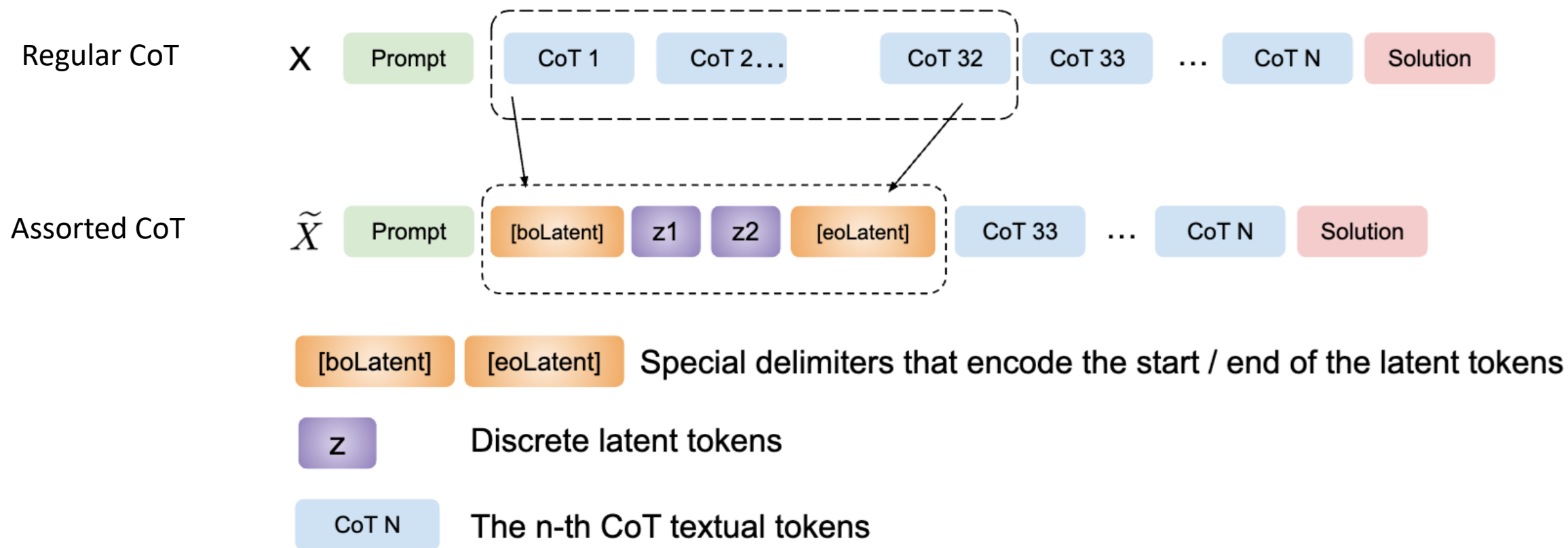
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- pause as thought	24.1 $\pm$ 0.7	2.2	100.0	3.0	98.2	8.2

Better performance than No-CoT
Shorter thinking process than CoT

Cons

1. Latent tokens are not interpretable
2. Only tested on GSM8k

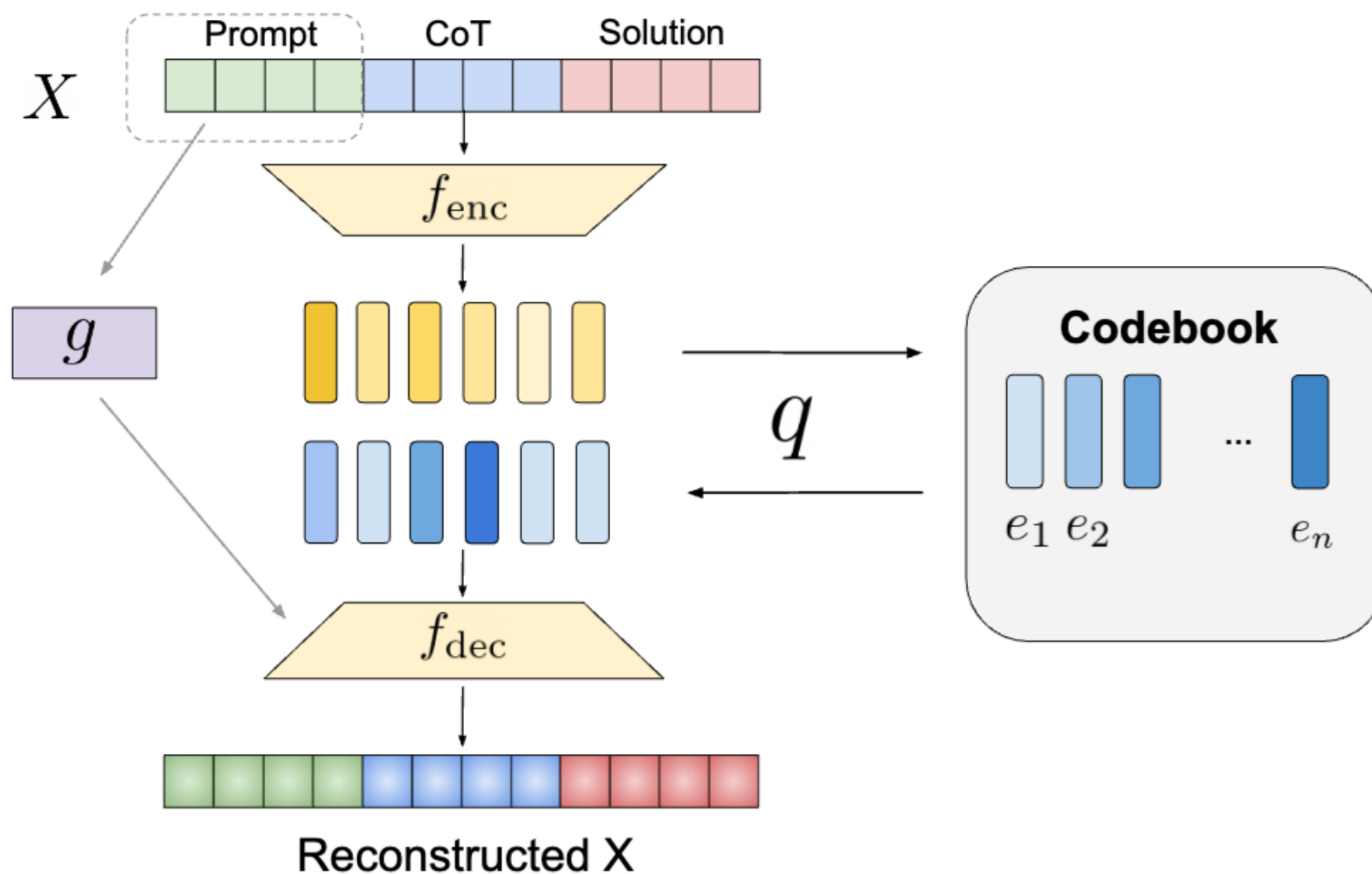
Token Assorted



Token Assorted

How the latent codes are constructed?

Using VQVAE



Better Performance

Model		In-Domain		Out-of-Domain					Average
		Math	GSM8K	Gaokao-Math-2023	DM-Math	College-Math	Olympia-Math	TheoremQA	All Datasets
Llama-3.2-1B	Sol-Only	4.7	6.8	0.0	10.4	5.3	1.3	3.9	4.6
	CoT	<u>10.5</u>	<u>42.7</u>	10.0	3.4	<u>17.1</u>	1.5	9.8	<u>14.1</u>
	iCoT	8.2	10.5	3.3	<u>11.3</u>	7.6	2.1	<u>10.7</u>	7.7
	Pause Token	5.1	5.3	2.0	1.4	0.5	0.0	0.6	2.1
	Latent (ours)	14.7 (↑ +4.2)	48.7 (↑ +6)	10.0	14.6 (↑ +3.3)	20.5 (↑ +3.4)	1.8	11.3 (↑ +0.6)	17.8 (↑ +3.7)
Llama-3.2-3B	Sol-Only	6.1	8.1	3.3	14.0	7.0	1.8	6.8	6.7
	CoT	<u>21.9</u>	<u>69.7</u>	<u>16.7</u>	27.3	<u>30.9</u>	2.2	11.6	<u>25.2</u>
	iCoT	12.6	17.3	3.3	16.0	14.2	4.9	13.9	11.7
	Pause Token	25.2	53.7	4.1	7.4	11.8	0.7	1.0	14.8
	Latent (ours)	26.1 (↑ +4.2)	73.8 (↑ +4.1)	23.3 (↑ +6.6)	<u>27.1</u>	32.9 (↑ +2)	<u>4.2</u>	<u>13.5</u>	28.1 (↑ +2.9)
Llama-3.1-8B	Sol-Only	11.5	11.8	3.3	17.4	13.0	3.8	6.7	9.6
	CoT	32.9	<u>80.1</u>	<u>16.7</u>	<u>39.3</u>	<u>41.9</u>	7.3	<u>15.8</u>	<u>33.4</u>
	iCoT	17.8	29.6	16.7	20.3	21.3	<u>7.6</u>	14.8	18.3
	Pause Token	39.6	79.5	6.1	25.4	25.1	1.3	4.0	25.9
	Latent (ours)	<u>37.2</u>	84.1 (↑ +4.0)	30.0 (↑ +13.3)	41.3 (↑ +2)	44.0 (↑ +2.1)	10.2 (↑ +2.6)	18.4 (↑ +2.6)	37.9 (↑ +4.5)

Shorter CoT

Model		In-Domain (# of tokens)		Out-of-Domain (# of tokens)					Average
		Math	GSM8K	Gaokao-Math-2023	DM-Math	College-Math	Olympia-Math	TheoremQA	All Datasets
Llama-3.2-1B	Sol-Only	4.7	6.8	0.0	10.4	5.3	1.3	3.9	4.6
	CoT	646.1	190.3	842.3	578.7	505.6	1087.0	736.5	655.2
	iCoT	328.4	39.8	354.0	170.8	278.7	839.4	575.4	369.5
	Pause Token	638.8	176.4	416.1	579.9	193.8	471.9	988.1	495
	Latent (ours)	501.6 (↓ -22%)	181.3 (↓ -5%)	760.5 (↓ -11%)	380.1 (↓ -34%)	387.3 (↓ -23%)	840.0 (↓ -22%)	575.5 (↓ -22%)	518 (↓ -21%)
Llama-3.2-3B	Sol-Only	6.1	8.1	3.3	14.0	7.0	1.8	6.8	6.7
	CoT	649.9	212.1	823.3	392.8	495.9	1166.7	759.6	642.9
	iCoT	344.4	60.7	564.0	154.3	224.9	697.6	363.6	344.2
	Pause Token	307.9	162.3	108.9	251.5	500.96	959.5	212.8	354.7
	Latent (ours)	516.7 (↓ -20%)	198.8 (↓ -6%)	618.5 (↓ -25%)	340.0 (↓ -13%)	418.0 (↓ -16%)	832.8 (↓ -29%)	670.2 (↓ -12%)	513.6 (↓ -20%)
Llama-3.1-8B	Sol-Only	11.5	11.8	3.3	17.4	13.0	3.8	6.7	9.6
	CoT	624.3	209.5	555.9	321.8	474.3	1103.3	760.1	578.5
	iCoT	403.5	67.3	444.8	137.0	257.1	797.1	430.9	362.5
	Pause Token	469.4	119.0	752.6	413.4	357.3	648.2	600.1	480
	Latent (ours)	571.9 (↓ -9 %)	193.9 (↓ -8 %)	545.8 (↓ -2 %)	292.1 (↓ -10%)	440.3 (↓ -8%)	913.7 (↓ -17 %)	637.2 (↓ -16 %)	513.7 (↓ -10%)

Main Theorem

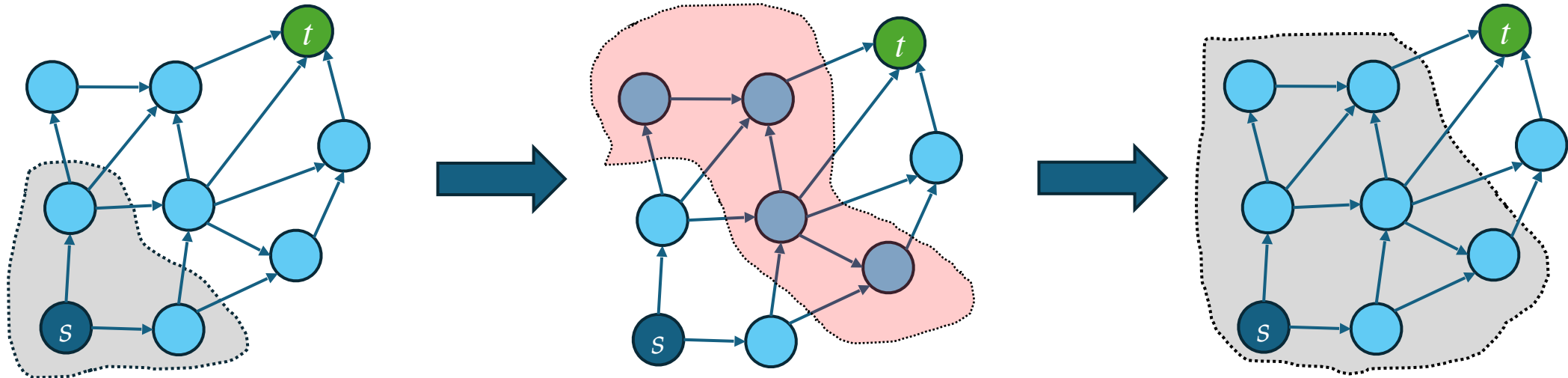
Theorem (informal)

For n -vertex directed graphs, a **2-layer** transformer with continuous CoT can solve reachability using $O(n)$ decoding steps with $O(n)$ embedding dimensions.

Best known results for discrete CoT: $O(n^2)$

Secret Sauce: Superposition of the embeddings!

Continuous CoT: Decoding as search



$$[t_1] = \frac{1}{\sqrt{|\mathcal{V}_1(s)|}} \sum_{v \in \mathcal{V}_1} \vec{u}_v$$

The embedding contains **superposition**

$$[t_2] = \frac{1}{\sqrt{|\mathcal{V}_2(s)|}} \sum_{v \in \mathcal{V}_2} \vec{u}_v$$

Mechanism of Emerged Representation

Representation

(Traditional) Symbolic
representation

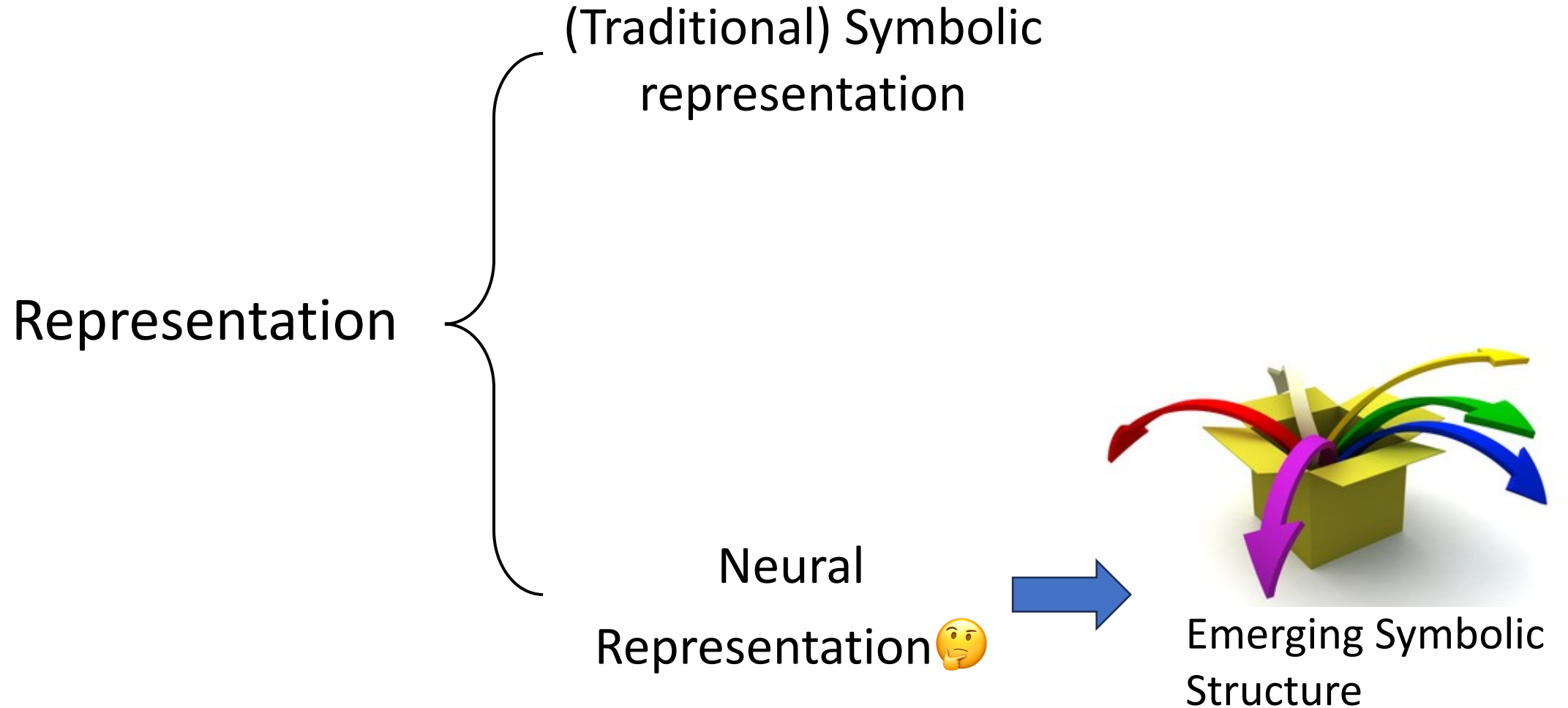
4 Conclusions

We have extended the GLU family of layers and proposed their use in Transformer. In a transfer-learning setup, the new variants seem to produce better perplexities for the de-noising objective used in pre-training, as well as better results on many downstream language-understanding tasks. These architectures are simple to implement, and have no apparent computational drawbacks. We offer no explanation as to why these architectures seem to work; we attribute their success, as all else, to divine benevolence.

Neural
Representation 🤔

*Shall we just acknowledge that
as “divine benevolence”?*

Mechanism of Emerged Representation



Modular Addition

$$a + b = c \bmod d$$

Does neural network have an *implicit table* to do retrieval?

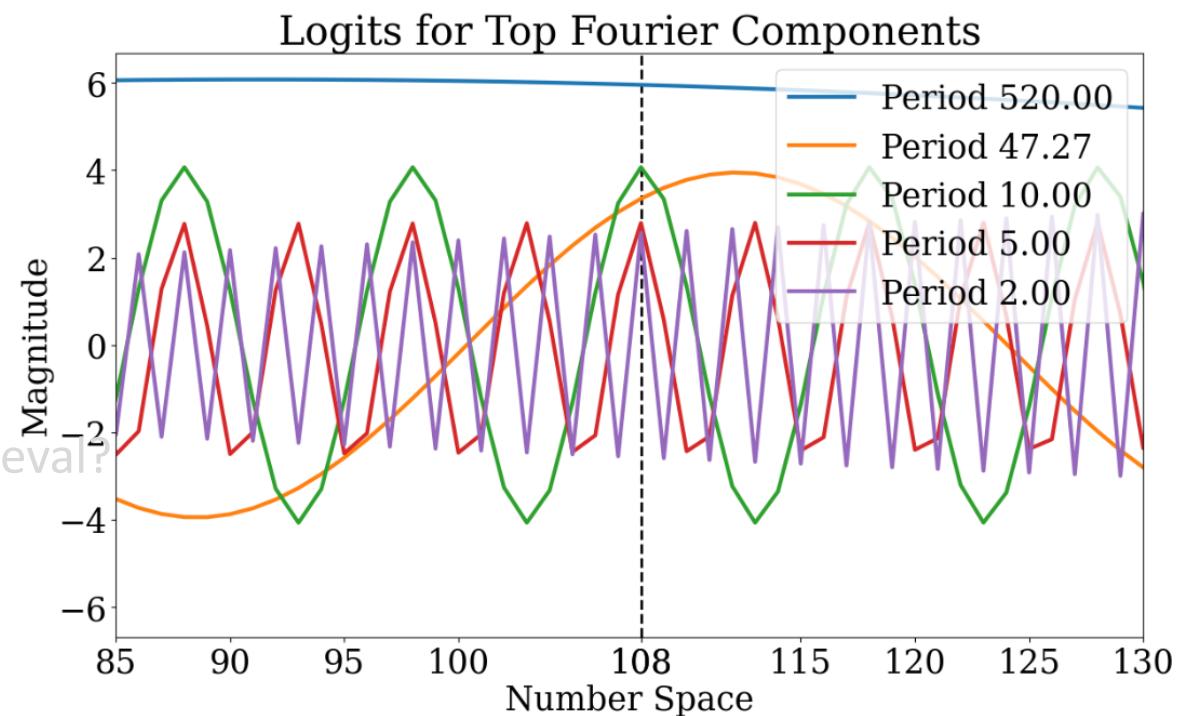
Modular Addition

$$a + b = c \bmod d$$

Does neural network have an *implicit table* to do retrieval?

Learned representation = Fourier basis 🧠💥

Why? 🤔



(a) Final logits for top Fourier components

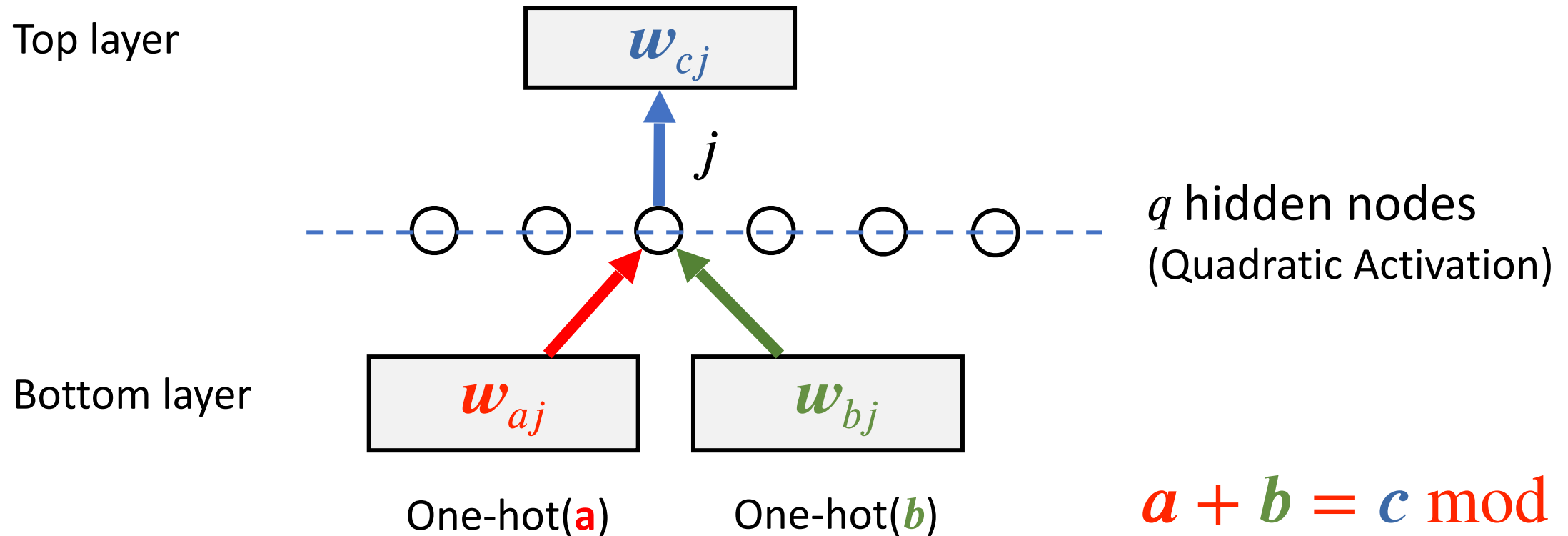
[T. Zhou et al, *Pre-trained Large Language Models Use Fourier Features to Compute Addition*, NeurIPS'24]

[S. Kantamneni, *Language Models Use Trigonometry to Do Addition*, arXiv'25]

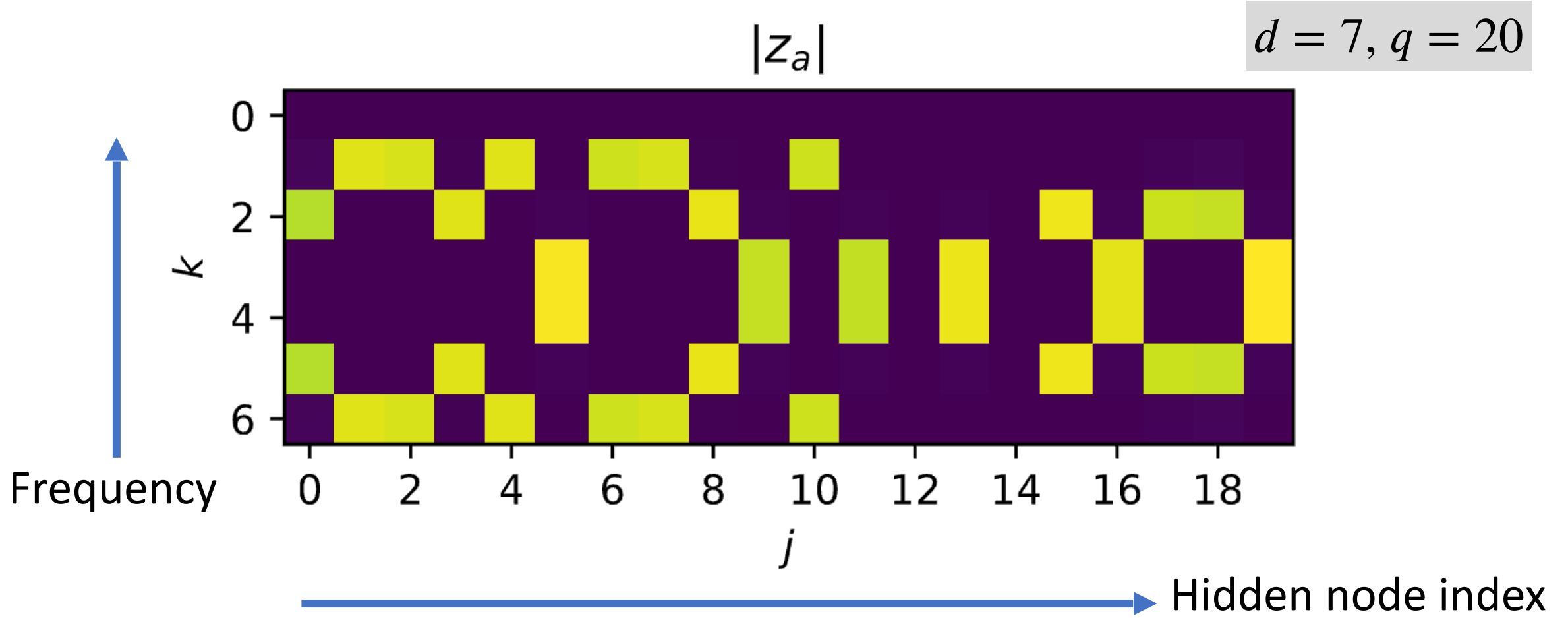
Minimal Problem Setup

MSE Loss: $\text{Min } \|\text{Output} - \text{one-hot}(\mathbf{c})\|_2$

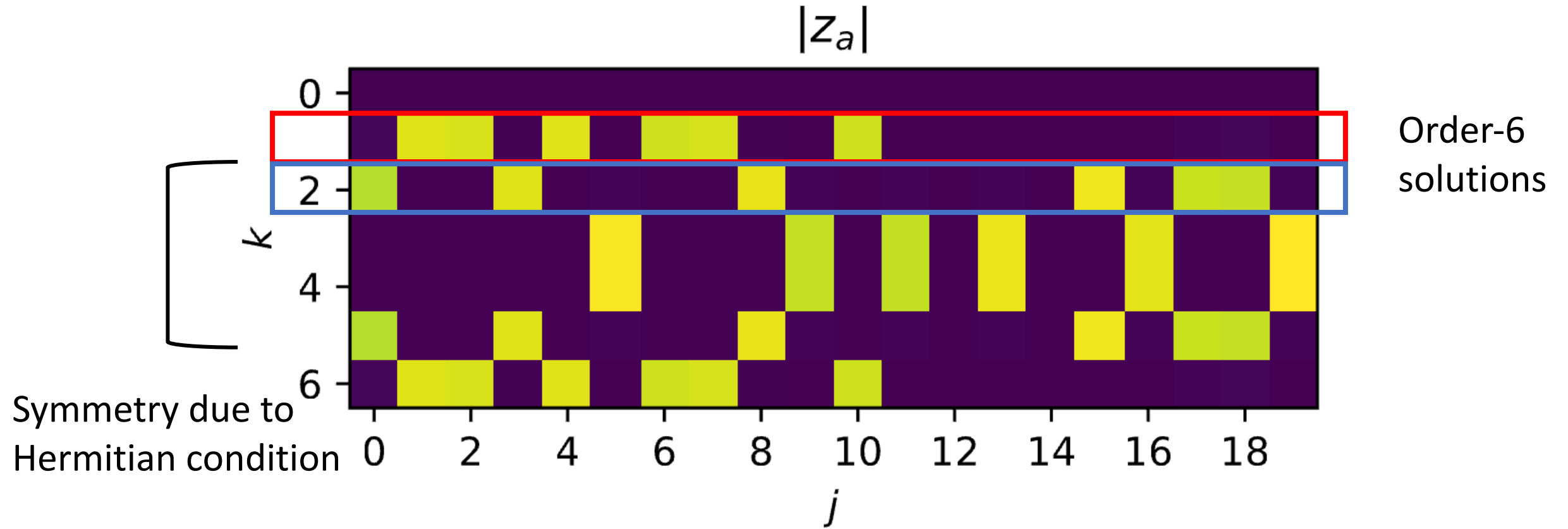
Top layer



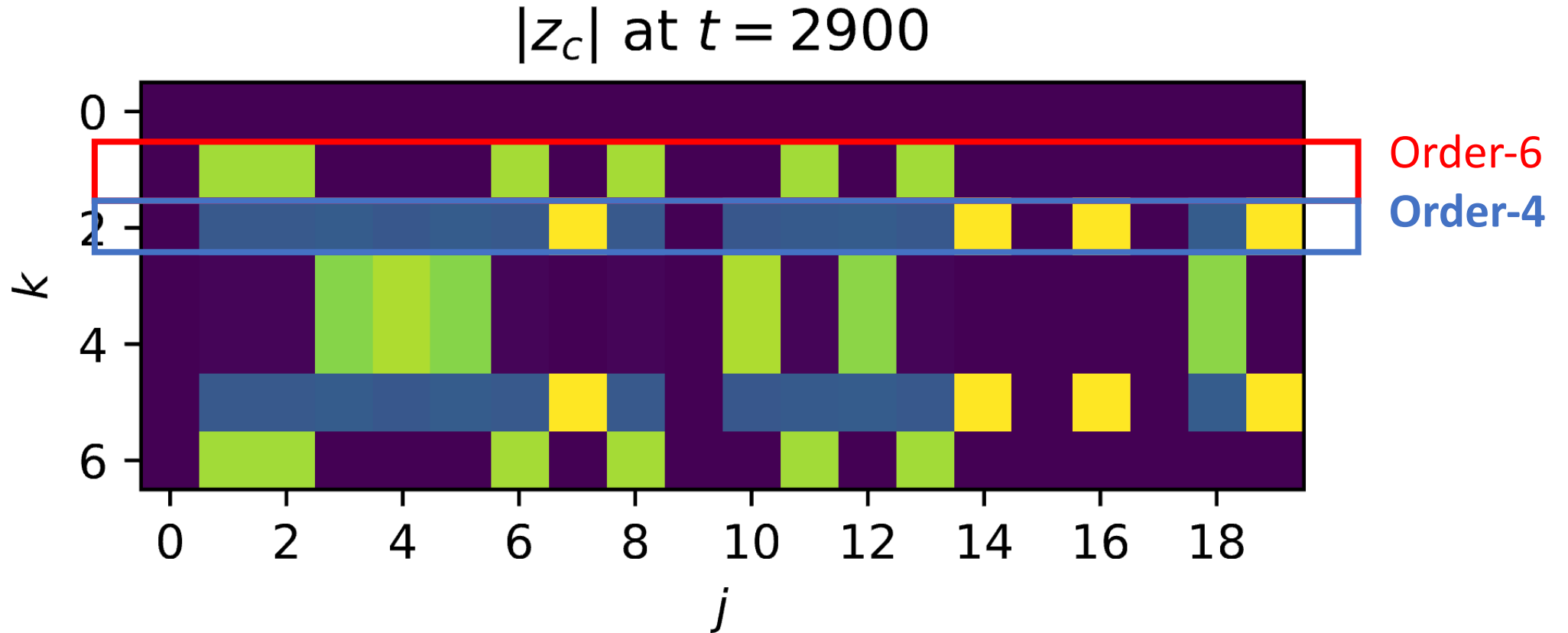
What a Gradient Descent Solution look like?



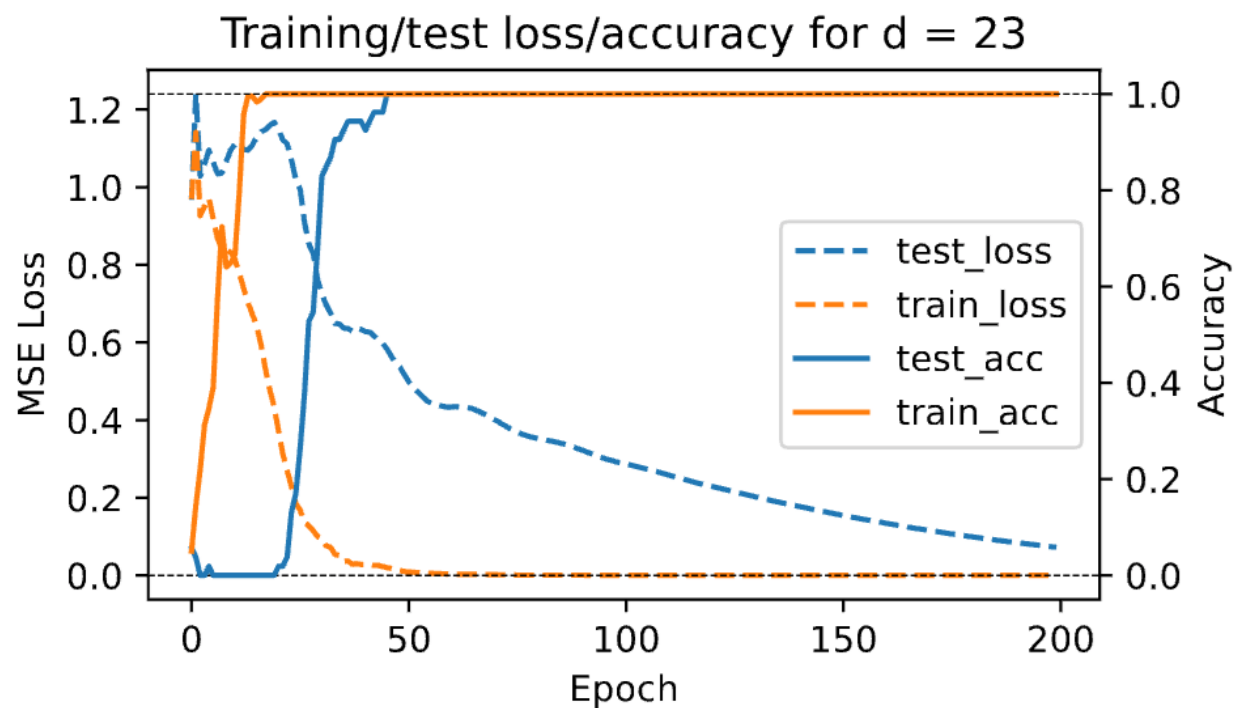
What a Gradient Descent Solution look like?



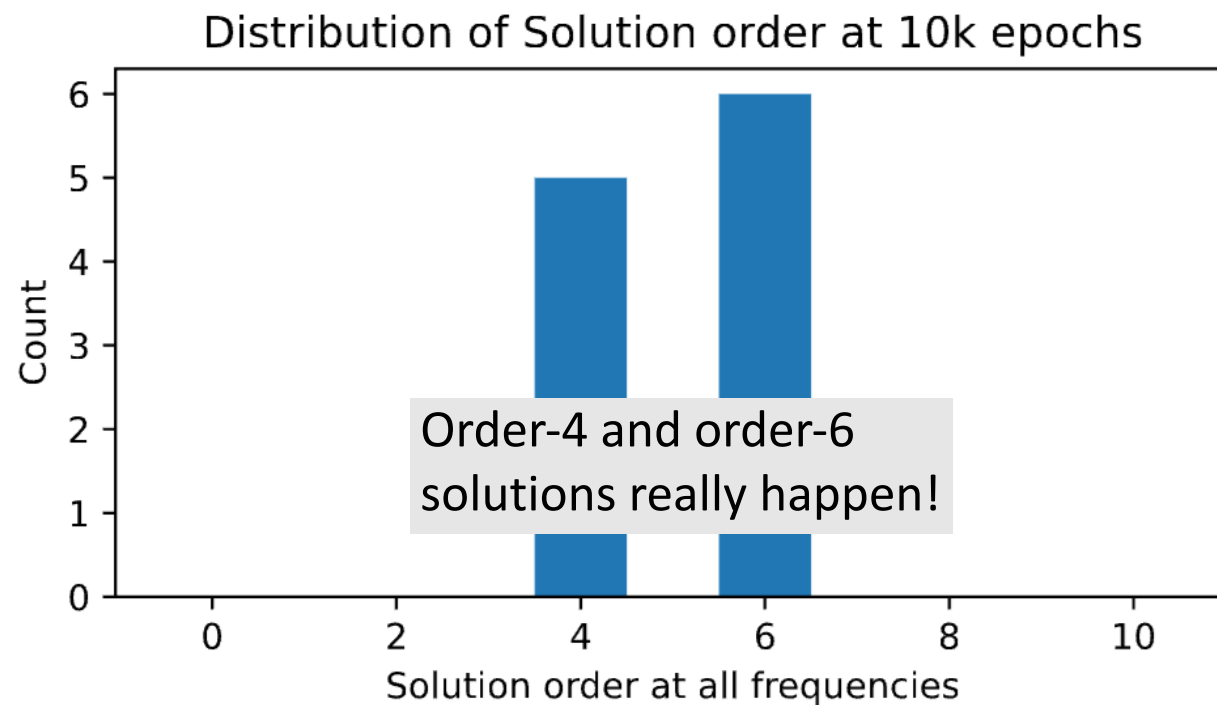
What a Gradient Descent Solution look like?



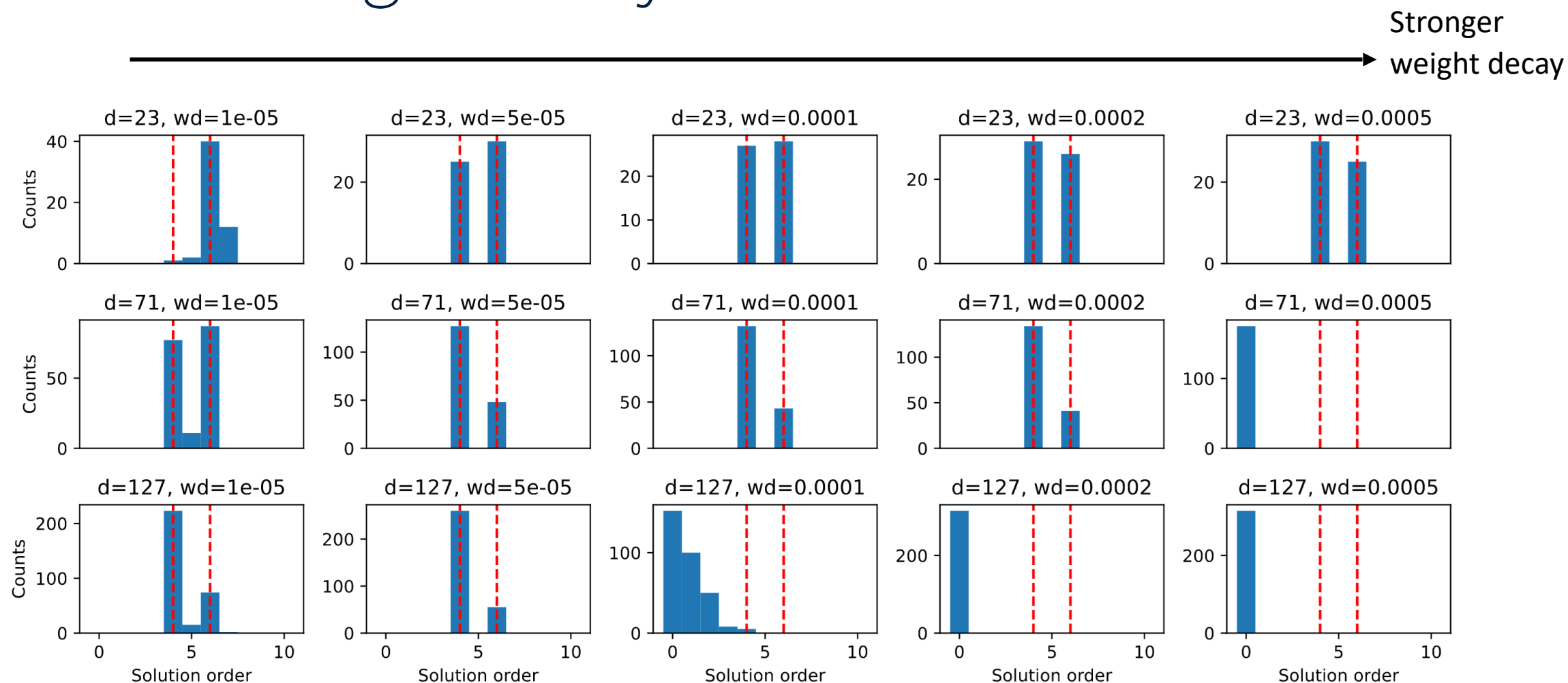
More Statistics on Gradient Descent Solutions



Grokking Behaviors!



Effect of Weight Decay



Theory to explicitly construct such solutions

Order-6 $\mathbf{z}_{F6}$ (2*3)

$$\mathbf{z}_{F6} = \frac{1}{\sqrt[3]{6}} \sum_{k=1}^{(d-1)/2} \mathbf{z}_{\text{syn}}^{(k)} * \mathbf{z}_{\nu}^{(k)} * \mathbf{y}_k$$

Theory to explicitly construct such solutions

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Order-4 $\mathbf{z}_{F4/6}$ (2*2)
(mixed with order-6)

$$\mathbf{z}_{F4/6} = \frac{1}{\sqrt[3]{6}} \hat{\mathbf{z}}_{F6}^{(k_0)} + \frac{1}{\sqrt[3]{4}} \sum_{k=1, k \neq k_0}^{(d-1)/2} \mathbf{z}_{F4}^{(k)}$$

Theory to explicitly construct such solutions

Order-6 $\mathbf{z}_{F6}$ (2*3)

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(mixed with order-6)

$$\mathbf{z}_{F4/6} = \frac{1}{\sqrt[3]{6}} \hat{\mathbf{z}}_{F6}^{(k_0)} + \frac{1}{\sqrt[3]{4}} \sum_{k=1, k \neq k_0}^{(d-1)/2} \mathbf{z}_{F4}^{(k)}$$

Perfect memorization
(order-d per frequency)

$$\mathbf{z}_a = \sum_{j=0}^{d-1} \mathbf{u}_a^j, \quad \mathbf{z}_b = \sum_{j=0}^{d-1} \mathbf{u}_b^j$$

$$\mathbf{z}_M = d^{-2/3} \mathbf{z}_a * \mathbf{z}_b$$

Gradient Descent solutions matches with construction

d	%not	%non-factorable		error ($\times 10^{-2}$)		solution distribution (%) in factorable ones			
	order-4/6	order-4	order-6	order-4	order-6	$z_{\nu=i}^{(k)} * z_{\xi}^{(k)}$	$z_{\nu=i}^{(k)} * z_{\text{syn},\alpha\beta}^{(k)}$	$z_{\nu}^{(k)} * z_{\text{syn}}^{(k)}$	others
23	0.0 $\pm$ 0.0	0.00 $\pm$ 0.00	5.71 $\pm$ 5.71	0.05 $\pm$ 0.01	4.80 $\pm$ 0.96	47.07 $\pm$ 1.88	11.31 $\pm$ 1.76	39.80 $\pm$ 2.11	1.82 $\pm$ 1.82
71	0.0 $\pm$ 0.0	0.00 $\pm$ 0.00	0.00 $\pm$ 0.00	0.03 $\pm$ 0.00	5.02 $\pm$ 0.25	72.57 $\pm$ 0.70	4.00 $\pm$ 1.14	21.14 $\pm$ 2.14	2.29 $\pm$ 1.07
127	0.0 $\pm$ 0.0	1.50 $\pm$ 0.92	0.00 $\pm$ 0.00	0.26 $\pm$ 0.14	0.93 $\pm$ 0.18	82.96 $\pm$ 0.39	2.25 $\pm$ 0.64	14.13 $\pm$ 0.87	0.66 $\pm$ 0.66

$$q = 512, \text{ } wd = 5 \cdot 10^{-5}$$

Gradient Descent solutions matches with construction

d	%not	%non-factorable		error ($\times 10^{-2}$)		solution distribution (%) in factorable ones			
	order-4/6	order-4	order-6	order-4	order-6	$z_{\nu=i}^{(k)} * z_{\xi}^{(k)}$	$z_{\nu=i}^{(k)} * z_{\text{syn},\alpha\beta}^{(k)}$	$z_{\nu}^{(k)} * z_{\text{syn}}^{(k)}$	others
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100% of the per-freq
solutions are order-4/6

Gradient Descent solutions matches with construction

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95% of the solutions are factorizable into “2*3” or “2*2”

Gradient Descent solutions matches with construction

d	%not order-4/6	%non-factorable		error ($\times 10^{-2}$)		solution distribution (%) in factorable ones			
		order-4	order-6	order-4	order-6	$z_{\nu=i}^{(k)} * z_{\xi}^{(k)}$	$z_{\nu=i}^{(k)} * z_{\text{syn},\alpha\beta}^{(k)}$	$z_{\nu}^{(k)} * z_{\text{syn}}^{(k)}$	others
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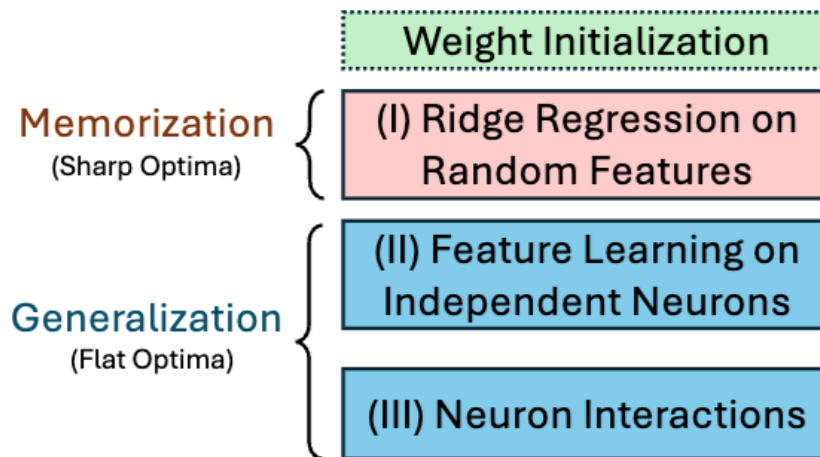
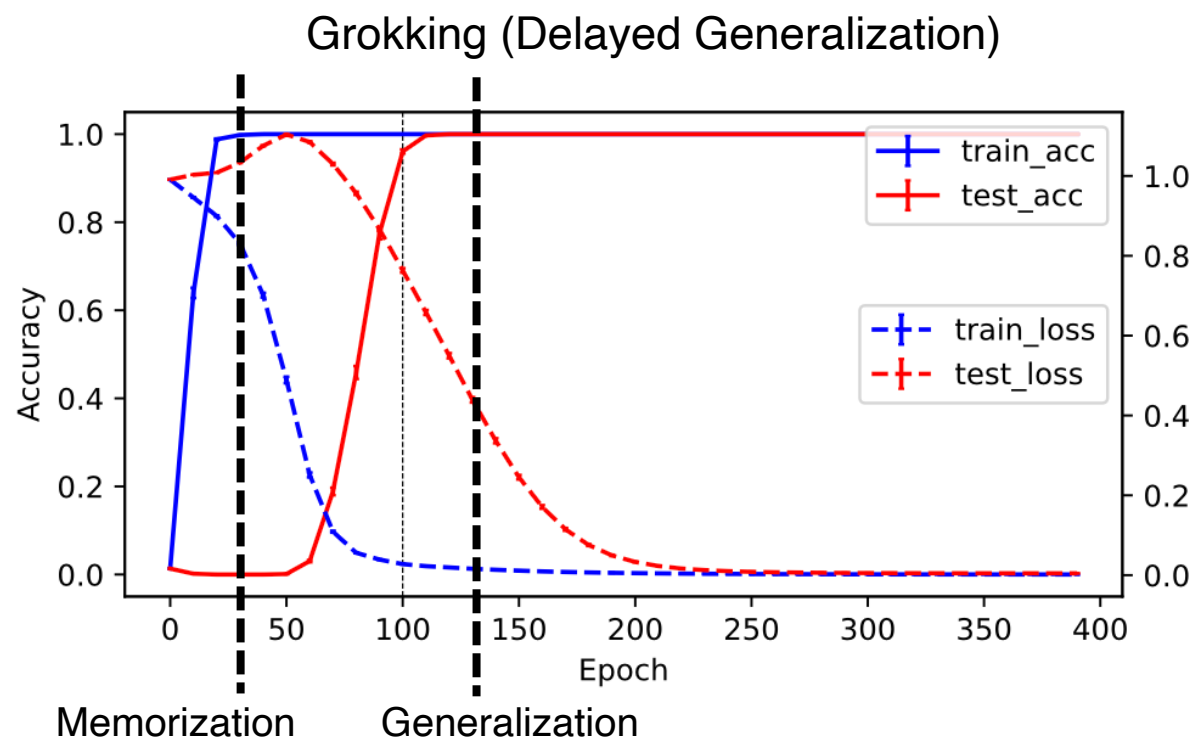
Factorization error is very small

Gradient Descent solutions matches with construction

d	%not		%non-factorable		error ($\times 10^{-2}$)		solution distribution (%) in factorable ones			
	order-4/6		order-4	order-6	order-4	order-6	$z_{\nu=i}^{(k)} * z_{\xi}^{(k)}$	$z_{\nu=i}^{(k)} * z_{\text{syn},\alpha\beta}^{(k)}$	$z_{\nu}^{(k)} * z_{\text{syn}}^{(k)}$	others
23	0.0 $\pm$ 0.0		0.00 $\pm$ 0.00	5.71 $\pm$ 5.71	0.05 $\pm$ 0.01	4.80 $\pm$ 0.96	47.07 $\pm$ 1.88	11.31 $\pm$ 1.76	39.80 $\pm$ 2.11	1.82 $\pm$ 1.82
71	0.0 $\pm$ 0.0		0.00 $\pm$ 0.00	0.00 $\pm$ 0.00	0.03 $\pm$ 0.00	5.02 $\pm$ 0.25	72.57 $\pm$ 0.70	4.00 $\pm$ 1.14	21.14 $\pm$ 2.14	2.29 $\pm$ 1.07
127	0.0 $\pm$ 0.0		1.50 $\pm$ 0.92	0.00 $\pm$ 0.00	0.26 $\pm$ 0.14	0.93 $\pm$ 0.18	82.96 $\pm$ 0.39	2.25 $\pm$ 0.64	14.13 $\pm$ 0.87	0.66 $\pm$ 0.66

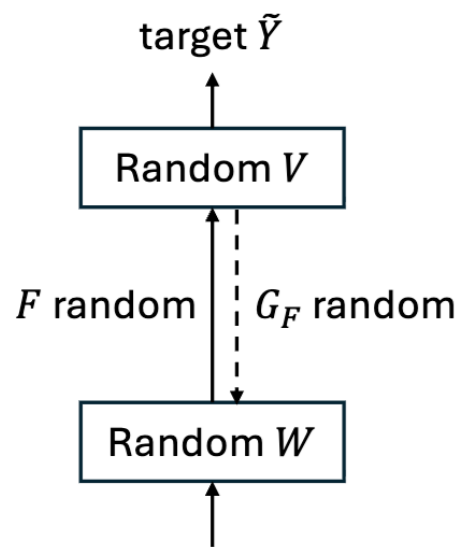
98% of the solutions can be factorizable into the constructed forms

Understanding Grokking

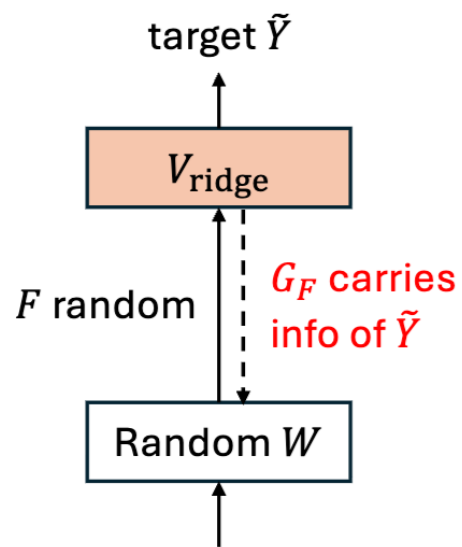


Stages of Grokking Behaviors

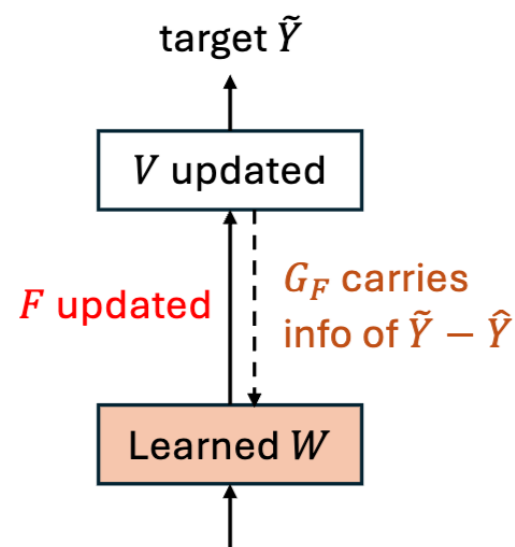
$$\hat{Y} = \sigma(XW)V$$



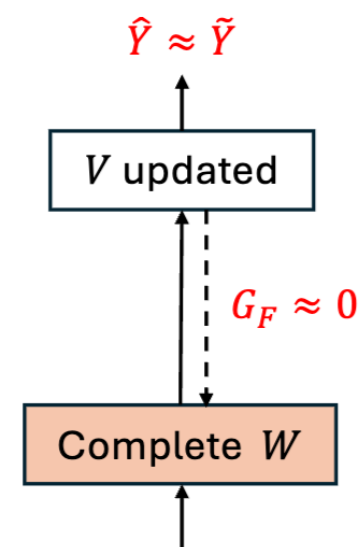
(a) Initialization



(b) After Lazy learning



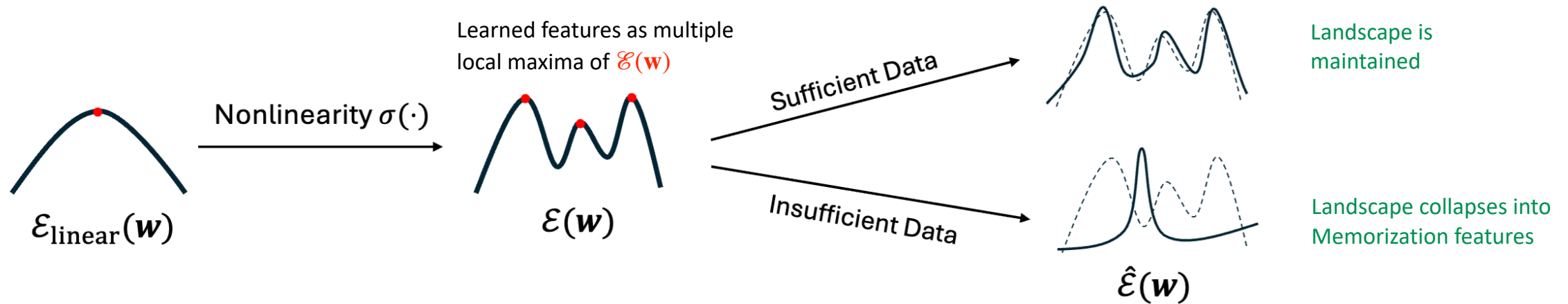
(c) After Independent Feature Learning



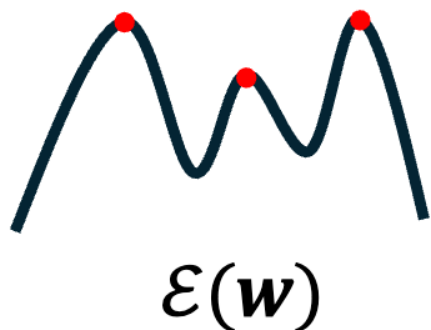
(d) After Interactive Feature learning

Connect Emerging Features with Data / Architecture

We discover that there exists an energy function $\mathcal{E}(\mathbf{w})$ that governs the feature learning process



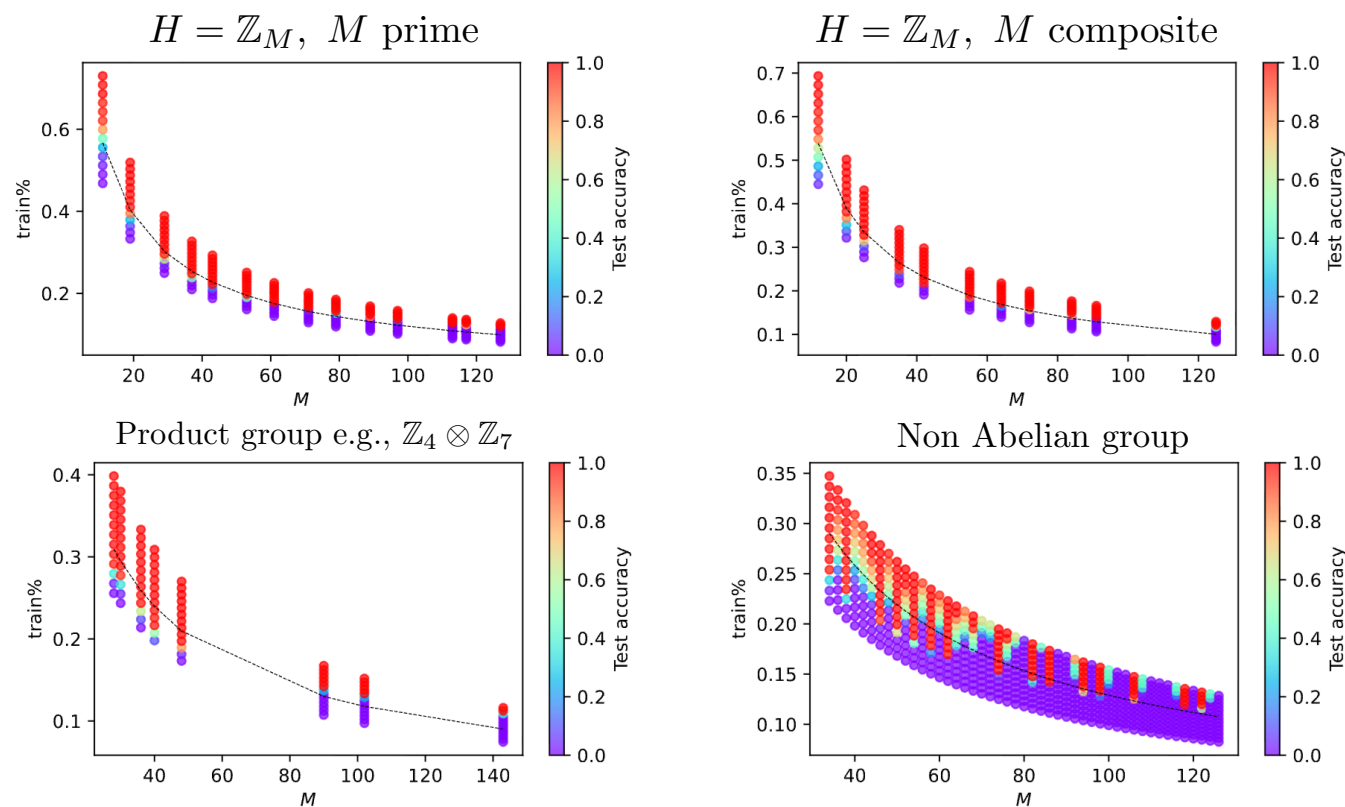
Emerging Features are Symbolic!



$$\mathcal{E}(\mathbf{w}) = \frac{1}{2} \sum_h \langle \tilde{R}_h, S \rangle_F^2 = \frac{M}{2} \sum_{k \neq 0} \frac{1}{d_k} \left| \sum_r \text{tr}(\hat{S}_{k,r}) \right|^2$$

Theorem 2 (Local maxima of $\mathcal{E}$ for group input). *For group arithmetics tasks with $\sigma(x) = x^2$, $\mathcal{E}$ has multiple local maxima $\mathbf{w}^* = [\mathbf{u}; \pm P\mathbf{u}]$. Either it is in a real irrep of dimension d_k (with $\mathcal{E}^* = M/8d_k$ and $\mathbf{u} \in \mathcal{H}_k$), or in a pair of complex irrep of dimension d_k (with $\mathcal{E}^* = M/16d_k$ and $\mathbf{u} \in \mathcal{H}_k \oplus \mathcal{H}_{\bar{k}}$). These local maxima are not connected. No other local maxima exist.*

How much is **sufficient**? Provable Scaling Laws



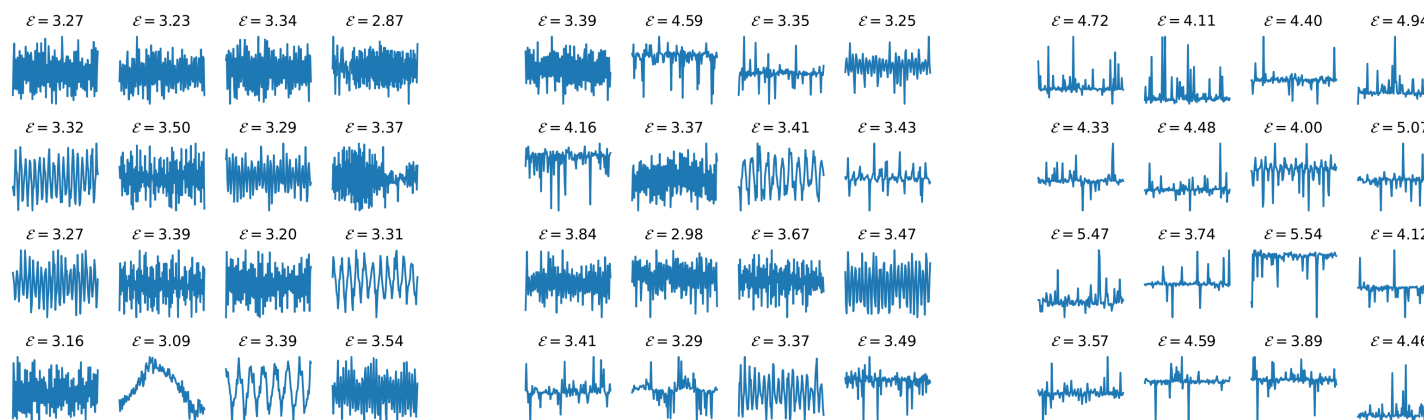
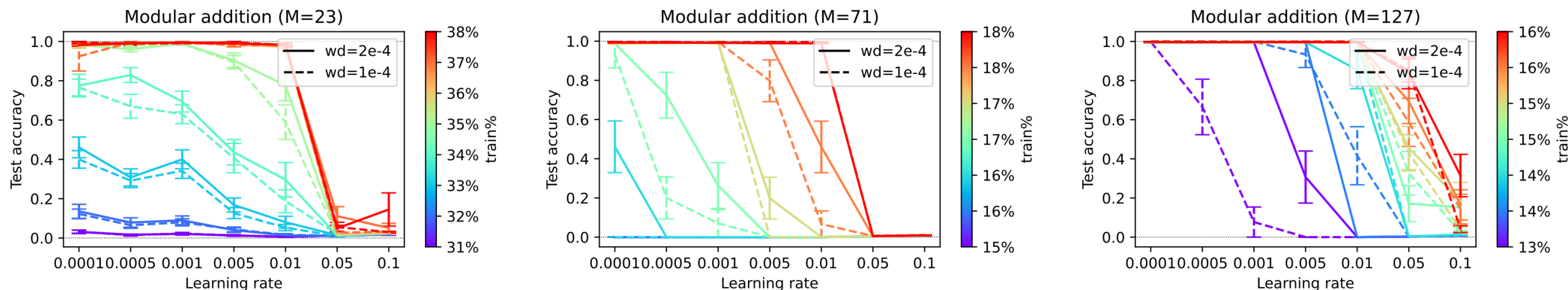
For Group Arithmetic tasks

Predict $h_1 h_2$, given $h_1, h_2 \in H$

$O(|H| \log |H|)$ data sample suffice to learn generalizable features

Next Step: Scale it to more complicated tasks and architectures

Boundary between Memorization and Generalization

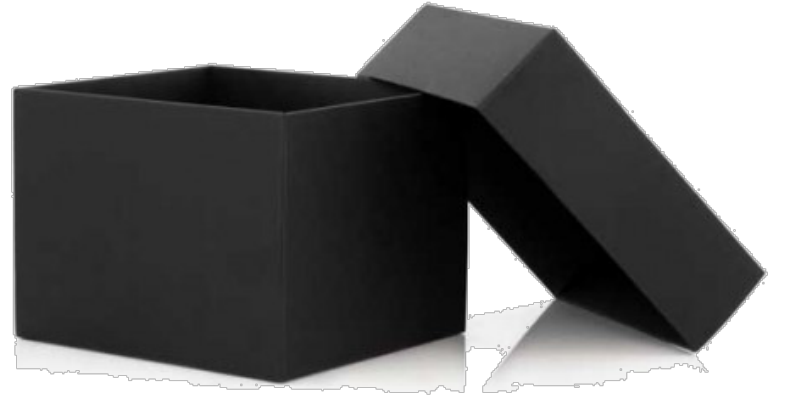
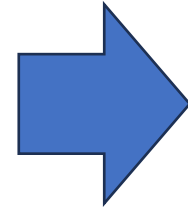


Possible Implications

Do neural networks end up learning more efficient **symbolic representations** that we don't know?

Does gradient descent lead to a solution that can be reached by **advanced algebraic operations**?

Will gradient descent become **obsolete**, eventually?



Thanks!